

Application of Parallel-hierarchical Transformations for Rapid Recognition of Dynamic Images Based on GPU Technology

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Abstract—The paper presents a method of parallel-hierarchical transformations for rapid recognition of dynamic images using GPU technology. Direct parallel-hierarchical transformations based on cluster CPU-and GPU-oriented hardware platform. Mathematic models of training of the parallel hierarchical (PH) network for the transformation are developed, as well as a training method of the PH network for recognition of dynamic images. This research is most topical for problems on organizing high-performance computations of super large arrays of information designed to implement multi-stage sensing and processing as well as compaction and recognition of data in the informational structures and computer devices. This method has such advantages as high performance through the use of recent advances in parallelization, possibility to work with images of ultra dimension, ease of scaling in case of changing the number of nodes in the cluster, auto scan of local network to detect compute nodes.

Keywords- parallel-hierarchical (PH) network, laser beam spot images, parallel-hierarchical (PH) transformation, fast recognition of dynamic images, GPU technology.

I. INTRODUCTION

Rapidly growing requirements to modern computational media encourage development of new intelligent methods of information transfer and processing. This problem can be solved through application of the laser-based technologies [1-3]. One of the most efficient methods of large data arrays processing is their parallel processing based on the neural-like parallel hierarchical systems. A goal of this paper is to develop and apply the suggested method and means of parallel hierarchical transformation for fast recognition of dynamic images. To increase a speed of computational structures, the method based on the normalizing equation was applied. It also allows performing a procedure of determination of weighting coefficients for each class [4].

II. THE METHOD OF PARALLEL HIERARCHICAL TRANSFORMATION WITH FORMATION OF THE NORMALIZING EQUATION FOR FAST IMAGE RECOGNITION

Algorithm and software package [5-7] realize the method of parallel hierarchical transformation with formation of the normalizing equation for fast image recognition, which is described in details in the previous works.

The research based on a masking method of information processing for purposes of fast recognition of laser beam spot images [8] suggests the need to improve a method of the parallel hierarchical transformation.

A number of hidden layer elements can be determined from the length of the network algorithm, accordingly formalizing a procedure for calculation of the number of hidden layer elements. Averaged values of weighting coefficients are determined by (1):

$$\bar{w}_t = \frac{\sum_{p=1}^N w_t^{(p)}}{N}, t = \overline{1, k-1}, \quad (1)$$

where N is a dimensionality of the taught sample P .

Let us compile a system of equations to determine tuning coefficients $w_1 \div w_{k-1}$ as system (2):

$$\begin{cases}
w_1 = \frac{\sum_{t=2}^k a_{11}^t}{(a_{11}^2 + \sum_i a_i^2)}, \\
w_2 = \frac{\sum_{t=2}^k a_{11}^t}{(a_{11}^3 + \sum_i a_i^3)} - \frac{w_1 a_{11}^2}{(a_{11}^3 + \sum_i a_i^3)}, \\
\cdots \\
w_{k-2} = \frac{\sum_{t=2}^k a_{11}^t}{(a_{11}^{k-1} + \sum_i a_i^{k-1})} - \frac{w_1 a_{11}^2 + w_2 a_{11}^3 + \cdots + w_{k-3} a_{11}^{k-2}}{(a_{11}^{k-1} + \sum_i a_i^{k-1})}, \\
w_{k-1} = \frac{\sum_{t=2}^k a_{11}^t}{(a_{11}^k + \sum_i a_i^k)} - \frac{w_1 a_{11}^2 + w_2 a_{11}^3 + \cdots + w_{k-2} a_{11}^{k-1}}{(a_{11}^k + \sum_i a_i^k)},
\end{cases} \quad (2)$$

Having compared the efficiency of the parallel hierarchical transformation [9-13] and known transformations by a number of computational operations used, a conclusion can be made that a number of operations for the PH transformation is $N(N+1)$, where N is a total number of elements processed.

III. EXPERIMENTAL RESULTS AND PHYSICAL MODELING OF THE PARALLEL HIERARCHICAL TRANSFORMATION FOR FAST RECOGNITION OF IMAGES OF LASER BEAM SPOTS

Four routes were used in experimental research of the parallel hierarchical transformation for fast recognition of images of laser beam spots [14-17]. Each route contains 100 frames. Using the normalizing equation (2), let us determine normalized measures for route 1 (Fig.1).

An average percentage of “good” images in this case is 40% and 59% respectively. Then the PH network is trained for repeated processing of “bad” route fragments [18].

47	2	3	57	5	12	7	8
10	20	6	13	14	15	16	17
19	11	21	22	23	68	25	26
38	29	64	31	32	33	35	34
37	28	39	49	53	42	41	52
46	1	48	40	61	51	44	43
55	71	4	58	69	62	50	60
30	65	66	67	24	59	70	56

a)

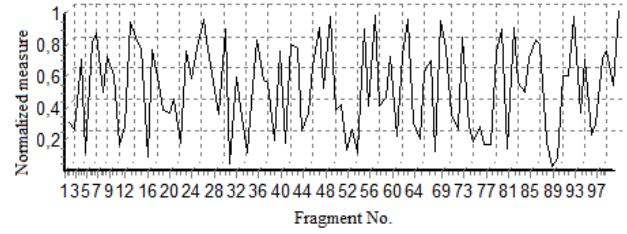


Figure 1. Normalized measures for route 1

Image processing is based on the GPU with cores realized at all elements covered by the initial region. The only obvious way to calculate a scalar of the input vector is a representation of 1x1 initial elements and use of the core read in all values from the input texture. This approach has several drawbacks [19, 20]. First, only one of parallel elementary processors would be busy. Second, that would probably exceed a maximum permitted by shader length and static instruction of calculation for some hardware. That is why we will perform a parallel operation of reduction based on global methods of communication on parallel computers.

At the high level, GPU-based parallel calculation is a correction of sizes of the input and output texture and index elements. For each of its elements, coordinates for input texture are corrected in such a way that they correspond to disconnected 2x2 subregions. Then values in those subregions are compared. This is repeated recursively until the 2x2 texture is reduced to the final one by the 1x1 “scalar” texture through a logarithmic series of repetitions [21-23].

Next series of images finalize the first step of reduction of the 8x8 algorithm of the input texture (Fig. 6). The left image demonstrates the input texture. Initial elements are marked in green (Fig. 2a). The right image is a result of the first round of reduction. Each initial element contains a local maximum of transfer of the 2x2 subregion in the input texture. This relation, in addition, is distinguished in the second line of images (Fig. 2b).

47	2	3	57	5	12	7	8
10	20	6	13	14	15	16	17
19	11	21	22	23	68	25	26
38	29	64	31	32	33	35	34
37	28	39	49	53	42	41	52
46	1	48	40	61	51	44	43
55	71	4	58	69	62	50	60
30	65	66	67	24	59	70	56

b)

Figure 2. The first step of reduction of the 8x8 algorithm of the input texture

Let us determine coordinates of energy centers of the fragment of route 1 (Fig. 3):

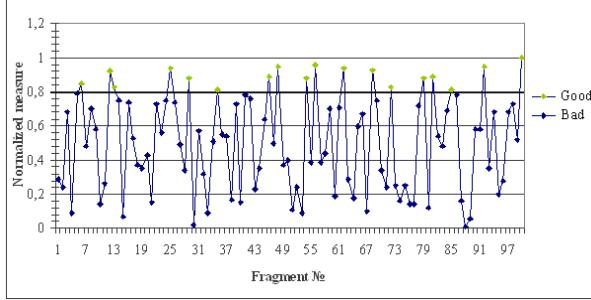


Figure 3. Graph of "good" and "bad" images formation in the track number 1.

A graphical interpretation of the distribution of coordinates of energy centers is shown in Fig. 4.

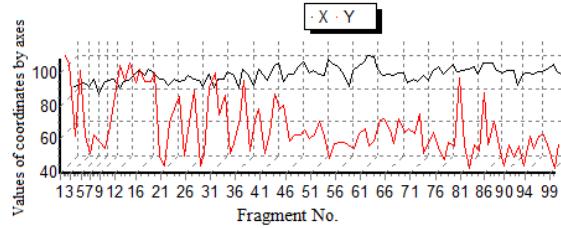


Figure 4. A graphic interpretation of the distribution of coordinates of energy centers

After the training of the PH network, a portion of "good" images was 83% (as compared to 18%).

The graphical interpretation of the determination of energy center coordinates after the PH network training is demonstrated in Fig. 5.

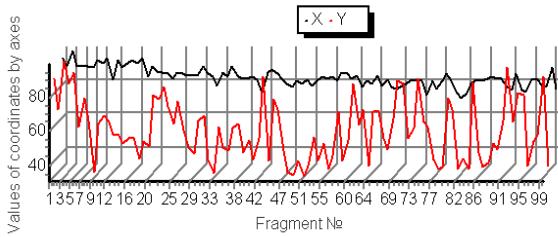


Figure 5. Determination of the energy centers coordinates for the fragments of route number 2

After training of the PH network percentage of "good" images on track number 2 was 76% (12% before training), Fig. 6.

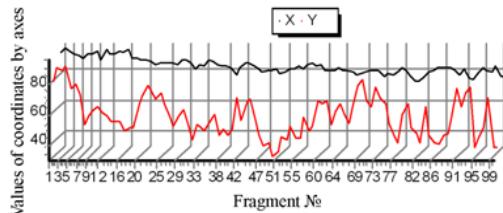


Figure 6. Determination of the energy centers coordinates for the fragments of route number 2 after PH network training

The graphical interpretation of the determination of energy center coordinates for route number 3 is demonstrated in Fig. 7.

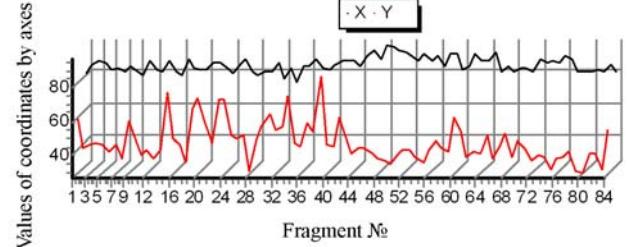


Figure 7. Determination of the energy centers coordinates for the fragments of route number 3

After training of the PH network percentage of "good" images on track number 2 was 65% (15% before training), Fig. 8.

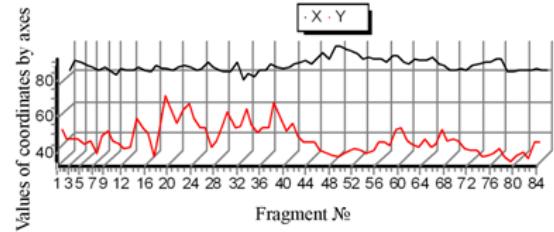


Figure 8. Determination of the energy centers coordinates for the fragments of route number 3 after PH network training

After training of the PH network percentage of "good" images on track number 2 was 83% (17% before training), Fig. 9.

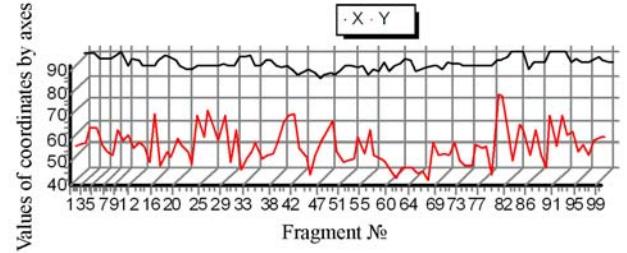


Figure 9. Determination of the energy centers coordinates for the fragments of route number 4 after PH network training

IV. CONCLUSIONS

The paper deals with a topical problem of increasing efficiency of recognition of dynamic images. The analysis of development of the PH transformation allows to attribute the suggested parallel hierarchical approach to neural methods of

transformation with a network of direct recognition and the space-time organization of connections. A method of the PH transformation with formation of the normalizing equation is developed. A method of PH transformation containing measures of tuning coefficients correspondence of the reference PH network and current network, was developed, as well as with finding a measure of correspondence of two networks as a whole.

Algorithms of processing and recognition of images of laser beam spots were developed. The developed algorithms allow determining a position of energy centers, classifying frames of images of the laser route.

On the basis of the developed algorithms, software was created for modeling a neural-like PH network. This software is used for classification and fast processing of images.

The method of PH transformations for rapid recognition of dynamic images using GPU technology has such advantages as high performance through the use of recent advances in parallelization, possibility to work with images of ultra dimension, ease of scaling in case of changing the number of nodes in the cluster, auto scan of local network to detect compute nodes [24, 25]. Decreasing of time required for pre-processing and network processing of laser routes image fragments should also be noted.

In [14-17] analysis of neural network technology using for extended laser route image classification was held. Computer simulation showed that the percentage of correctly recognized images was 92.5%, moreover 74% of "good" images and 60% of "bad" ones. In [15] simulation of recognition system based on neural network MLP and neural network based on radial basis function (RBF) was conducted. During recognition the sample of 140 spots-images of laser route by neural network based on RBF, modeled in the package Statistica Neural Networks 4.0, 92% of correctly recognized images received. Comparing the results of [14, 15] and the results of this paper we can talk about the availability of the last one.

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