

An Efficient Biogeography based Face Recognition Algorithm

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Abstract—Extracting the optimal features from images is always required in face recognition algorithm to achieve high accuracy. In this paper we have presented an efficient face recognition algorithm based on Biogeography Based Optimization (BBO). First we extract the features using the principal Component Analysis (PCA) after applying gabor filters and then we apply BBO to get the most desirable features. The proposed biogeography based face recognition algorithm is applied to search the most desirable features based on well defined fitness function. Performance analysis is performed using Olivetti Research Laboratory (ORL) face database. Performance results show that biogeography based face recognition algorithm generates better results than the original PCA technique with gabor filters.

Keywords—Face Recognition, Biogeography Based Optimization, PCA, Gabor Filter

I. INTRODUCTION

There is a lot of research avenues in the field of face recognition due to challenges present in the field. The goal of face recognition is to match a given image against a large database of images to check its presence. The face recognition has been applied to two most important applications i.e verification (one to one matching) and identification (one to many matching) [9]. Researchers have presented a lot of techniques for face recognition [1]. These techniques can be categorized as holistic matching method for e.g Principal Component Analysis (PCA) and local feature matching method [2]. In this paper we will focus on PCA. One of the biggest challenges in PCA is that we cannot use it on raw images directly. They need to be properly aligned and uniformly illuminated. This challenge can be solved using gabor filters which takes a raw image, generates gabor filter response and convert the raw image into properly aligned and constantly illuminated image. We have explored the research that showed that Gabor PCA based method for face recognition outperforms PCA based Eigenface method [3]. To improve further this hybrid technique we applied BBO to further optimize the desirable features from the image and go on to illustrate that in our results.

A. Principal Component Analysis

Extraction of features from the images is the foremost step in face recognition. PCA is a standard technique used for feature extraction. The image in the form of $A \times A$ matrix can be expressed as a point in the space $A \times A$ dimensions. The goal of PCA is to find the required vectors

that can represent the image information and form another space. PCA steps are as follows:

1. Let the training set of face images be $\Gamma_1, \Gamma_2, \Gamma_3, \dots, \Gamma_p$.
2. We calculate the average face of the set by $\psi = \frac{1}{p} \sum_{r=1}^p \Gamma_r$.
3. We calculate the difference of each face from the average by vectors $\phi = \Gamma_i - \psi$.
4. We calculate eigenvalues and eigen vectors from covariance matrix as shown (1) and a new face image is transformed into its face components by this operation [2].

$$c = \frac{1}{p} [\sum_{R=1}^p \phi_R \phi_R^T] \quad (1)$$

5. We calculate weights using (2) and from them we form a vector $\Omega = \omega_1, \omega_2, \dots, \omega_p$ that represents the contribution of each eigenvector in representation of input face image.

$$\omega_k = \mu_k^T (\Gamma - \psi), k = 1, 2, \dots, P \quad (2)$$

where μ_k is eigen vector.

These weights may be used in a face classification algorithm to find which of predefined face classes that describe the face [12].

B. Gabor Filters

Gabor filters generally called as Gabor wavelets or kernels are complex band pass filters. They have shape similar to the shape of the cells of the visual cortex of mammalian brains. These are used in many applications such as extraction of multiresolutional, spatially local features of a confined frequency band [5]. Another important feature of the =Gabor filters is that they act as an efficient tool for facial feature extraction and robust face recognition [3]. In general the family of 2D Gabor filters can be defined in the spatial domain in the following manner. [4, 6, 7, 8, 9]:

$$\psi_{u,v}(a, b) = \frac{f_u^2}{\pi \kappa \eta} e^{-((f_u^2/\kappa^2)a^2 + (f_u^2/\eta^2)b^2)} e^{j2\pi f_u a} \quad (3)$$

Where $a = a \cos \theta_v + b \sin \theta_v$, $b = -a \sin \theta_v + b \cos \theta_v$, $f_u = f_{max}/2^{(u/2)}$ and $\theta_v = v\pi/8$.

Each gabor filter represents a gaussian kernel function modulated by complex plane wave whose center frequency and orientation are given by f_u and θ_v , respectively. The parameter κ and η determine the ratio between center frequency and size of Gaussian envelope. Though we can have different values for above mentioned parameters determining characteristics of the filters, the most common

parameters used for face recognition are $\kappa = \eta = \sqrt{2}$ and $f_{\max} = 0.25$ [6,7,8,9]. When using gabor filters for facial feature extraction, researchers typically construct a filter bank featuring filter of five scale and eight orientation (comprised of 40 filters as shown in Fig. 1), that is $u = 0, 1, \dots, p-1$ and $v = 0, 1, \dots, r-1$, where $p = 5$ and $r = 8$ [4].

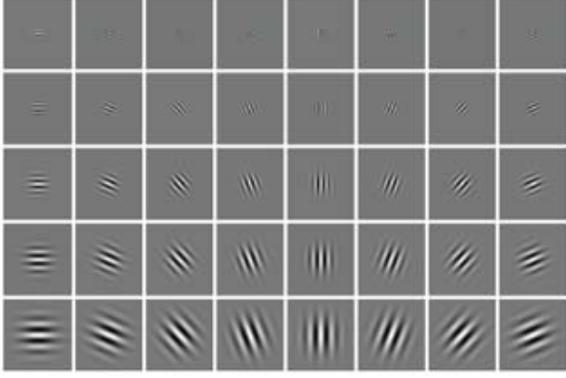


Figure 1. The real parts of the Gabor filter bank commonly used for feature extraction in the field of face recognition [4].

C. Principal Component Analysis of gabor filters

First we need to apply gabor filter to the raw images to generate gabor filter response and then these gabor filter response act as input to the PCA. The whole process till now is shown in the Fig. 2. Gabor filter provides robustness against varying contrast and brightness. It can also represent characteristic of local face area.

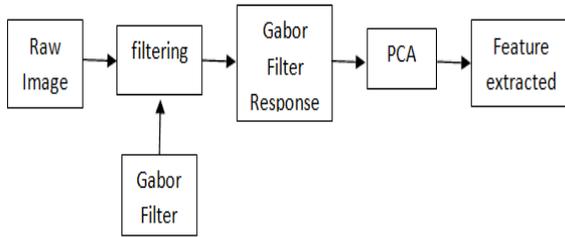


Figure2. Features extraction

Let $D(a, b)$ be a grey scale image of size $m \times n$ pixels and let $\psi_{u,v}(a, b)$ denote a gabor filter given by its center frequency f_u and orientation θ_v . The filtering operation of the given face image $D(a, b)$ can be defined as [4, 6, 7, 8, 9]

$$M_{u,v}(a, b) = D(a, b) * \Psi_{u,v}(a, b) \quad (4)$$

Where $M_{u,v}(a, b)$ denote the gabor filter response which can be decomposed into real ($E_{u,v}(a, b)$) and imaginary part ($O_{u,v}(a, b)$).

$$E_{u,v}(a, b) = \text{Re}[M_{u,v}(a, b)] \quad (5)$$

$$O_{u,v}(a, b) = \text{Im}[M_{u,v}(a, b)]$$

D. Selecting Optimal features using BBO

We extract the features using the principal component analysis of gabor filter. But further we need to find the most optimal set of features without compromising accuracy. In the proposed algorithm we are using an evolutionary algorithm based on swarm intelligence known as BBO [14]. BBO is explained in the next section [10].

E. Biogeography based optimization

Biogeography is the study of geographical distribution of biological organisms. It aims to learn how species migrate from one island to another. Biogeography is expressed in terms of various factors such as habitat area, immigration rate, emigration rate, habitat suitability index (HSI) and suitability index variables (SIV). Each individual is considered as a ‘‘habitat’’ with a habitat suitability index to measure individual. Suitability index variables (SIV) are those variables of an individual by which we can characterize habitability. A good solution always has a high HSI and a poor solution has low HSI. A good solution shares its features with the poor ones using migration [11, 13, 15, 16].

II. PROPOSED APPROACH FOR USING BBO

After features are extracted using gabor filter and PCA. The extracted features are further minimized using BBO. The final feature subset consists of the most optimal features. Table 1 shows some information about the BBO.

A. Suitability Index Variable

In the proposed approach the habitat represents a possible solution (optimal features). The habitat comprises of several Suitability Index Variable (SIVs). Features extracted from every single image represent a SIV.

B. Habitat Suitability Index and Fitness Function

Each habitat is evaluated on the basis of habitat suitability index (HSI). Habitat Suitability Index can be considered as a value return by the fitness function. A habitat is considered rich in features if its HSI value is closer to the ideal habitat’s HSI value and if its value is far from the ideal HSI value then the habitat is considered as a poor habitat containing less features. Based on the HSI value we can always distinguish between good solution and the bad ones. In order to improve the bad solutions we can migrate certain set of selected features from the ideal solution to bad ones. We have used standard mean as the fitness function for the approach. After developing the training model we use Euclidean distance to calculate the matching score between the features of test image and that of training model.

C. Distance Calculation

After the development of train model from the training set images, we calculate the similarity matrix using the matrix which contains the features extracted from test set of images. The distance used to compute the similarity matrix is ‘Euclidean’. Euclidean distance is the straight line

distance between two points present in a N-dimensional space. For example, the Euclidean distance between any two points x_i and y_i present in N-dimensional space is given by [10]:

$$D = \sqrt{\sum_{i=1}^N (x_i - y_i)^2} \quad (6)$$

TABLE 1. BBO PARAMETERS

Number of iterations of BBO algorithm	120
SIV value	Real
Number of SIVs in a Habitat	120

Extract the features from the training set and test set in matrices as shown in Fig. 2 using Gabor filter and PCA. Let's say 'train_data' is a matrix contains feature extracted from training set and 'test_data' contains features extracted from test set.

1. Calculate the hsi value for the whole train data using fitness function. It will be treated as ideal HSI.
2. Apply BBO for 120 (number of SIVs) iterations and in each iteration do the following :
 - a. Calculate HSI value for the SIV (or column) of the image present in test_data matrix.
 - b. Compare the calculated HSI value with ideal HSI.
 - c. If calculated HSI value is close to ideal HSI do nothing. Go to next iteration.
 - d. If calculated HSI is not close to ideal HSI then perform migration to improve test_data.
3. Calculate similarity matrix from train_data and test_data using euclidean distance and plot the required curve.

Figure 3: Proposed BBO Algorithm for face recognition.

III. DATABASE AND EXPERIMENTAL SETUPS

For our biogeography based face recognition algorithm we use standard ORL database acquired at the Olivetti Research Laboratory in Cambridge, U.K. The database consists of 400 distinct images that correspond to 40 distinct subjects. Therefore, each subject has 10 facial images each image has got different illumination, pose and facial expression. The size of each image is 92 x 112 pixels and has 8-bit grey levels [9]. Some of the images from the ORL database are shown below in Fig. 4.



Figure 4: Representative set of ORL face database

For our experiment we have used 360 images that is six images per subject. We have divided the images of every subject into two sets. First set (training set) contains the first three images of every subject. Second set (test set) contains the next three images of every subject. So, both training set and test set consists of 120 images each. Training set trains the system and build the train model. Test set is used for assessment and calculation of certain parameters. We develop the train model from the training set by applying gabor filter and PCA and use the same techniques to extract features from test set. Both training set and features extracted from test set images are matrices of size 119 x 120. Each column represents an image or a SIV of length equal to 119. Now, we apply BBO to the features extracted from the test set and use train model as ideal habitat.

IV. PERFORMANCE ANALYSIS

For performance analysis of our biogeography based face recognition algorithm we calculate the similarity matrices, in which each of the image vector is compared with each image vector present in the train model and client and imposter matching scores are calculated. A client is an entity who is making a genuine identity claim whereas imposter is the one making a false identity claim. We calculate performance metrics from the similarity matrix like false acceptance rate (FAR), false rejection rate (FRR), half total error rate (HTER), verification rate at 1%, .1% and 1, etc [4].

$$FRR = (a/b) \times 100\% \quad (6)$$

Where a = number of rejected genuine identity claims and b = total number of genuine claims made.

$$FAR = (c/d) \times 100\% \quad (7)$$

Where c = number of accepted false identity claims and

d = number of false identity claims made.

And HTER is given by

$$HTER = 0.5(FAR + FRR) \quad (8)$$

And verification rate is equal to 1-FRR.

Now, in order to show the efficiency of the proposed biogeography based algorithm we have plotted the receiver operating characteristic (ROC) curve having verification rate on the Y-axis and False Acceptance rate on X-axis. We have plotted two ROC curves in Fig. 5. In Fig. 5 the lower dashed line shows the ROC curve for simple gabor filter and PCA technique without applying BBO and the upper solid line shows the ROC curve for the proposed BBO

based algorithm. Clearly, the proposed biogeography based algorithm shows better verification rate

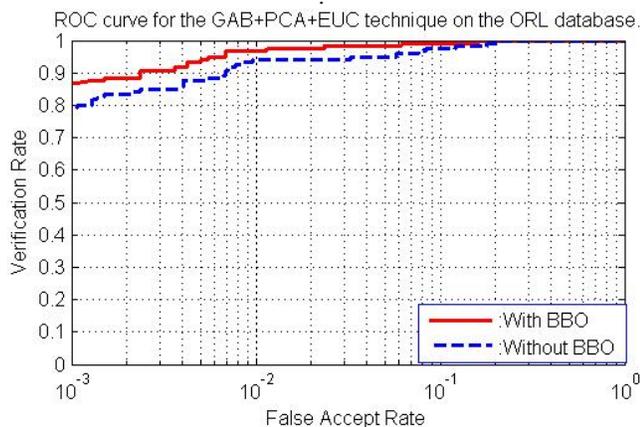


Figure 5. ROC curve for gabor and PCA technique.

V. CONCLUSION

In this paper, we propose an efficient biogeography based face recognition algorithm. We apply Biogeography Based Optimization (BBO) to the features extracted from test set of images after applying gabor filters and PCA as shown in Fig. 2. The proposed algorithm tries to find the most optimal set of features from the images. The performance is evaluated using the standard ORL face database. The results obtained in Fig. 5 shows that the proposed biogeography based algorithm shows better verification rate than the normal face recognition algorithm.

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