Buck Chopper Simulation Based on MATLAB

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Abstract. Based on MATLAB software, buck circuit is simulated to deepen the understanding of buck chopper circuit principle. In this paper, the basic working principle of buck circuit is briefly described, and the component parameters of the circuit are designed. Based on the MATLAB visual simulation tool - Simulink, for several working modes of induced current, change the parameters and observe the output results. Compared with the theoretical knowledge, the research on DC / DC converter is simpler and more intuitive.

1. Simulation Environment and Tool Box

Simulation environment: MATLAB, Simulink
Tool-box: Start → Simulink → SimPowerSystems [1]

2. Simulation Circuit

Fig 1. The simulation circuits

3. Parameter Setting

3.1 Parameter Hypothesis.

a. Input Voltage \( V_d = 200V \);
b. Output Voltage \( V_o = 50V \);
c. Ripple voltage is 1% of the output voltage;
d. Load resistance \( R = 10\Omega \);
e. Operating frequency \( f = 10kHz \)

According to the equation:
Duty cycle: \( D = \frac{V_o}{V_d} = \frac{50}{200} = 0.25 \);
Load current: \( I_o = \frac{V_o}{R} = \frac{50}{10} = 5A \);

3.2 Calculation in Critical Condition.

ripple voltage:
\[
\frac{\Delta V_o}{V_o} = \frac{T^2 (1 - D)}{8LC} = 1\%
\]

current condition:
\[
I_{LB} = I_{GB} = \frac{DT_o (V_d - V_o)}{2L}
\]

According to the following equations:
Inductance: \( L = 0.375mH \);
Capacitance: \( C = 0.25mF \);

3.3 Parameters in Simulate Circuit.

3.3.1 Continuous Current Working Mode.

In order to make the inductive current continuous, the actual inductance value is 1.2 times about
the threshold value \([2]\). So, the value of the inductance is, currently, according to the equation, the
value of the capacitance is \( C = 0.000208F \).

3.3.2 Discontinuous Current Mode.

1) is invariant
Only change the, make the value of increase, the other parameters are invariant.

2) Is invariant
Adjust decrease to make the current discontinuous.

4. Simulation Result

4.1 Continuous Current Working Mode.

When the actual inductance value is 1.2 times about the threshold value. So, the value of the
inductance is \( L = 0.45mH \), the value of the capacitance is \( C = 0.000208F \).

Fig 2. \( D = 25\% \)
Fig 3. \( D = 50\% \)
Fig 4. \( D = 75\% \)

4.2 Critical Condition.

Fig 5. \( D = 25\%, R = 10\Omega \)
4.3 Discontinuous Current Mode.

4.3.1 \( V_d \) is Invariant.

Fig 6. \( V_d \) is invariant \( D = 25\%, R = 20\Omega \)

Fig 7. \( V_d \) is invariant \( D = 25\%, R = 50\Omega \)

4.3.2 \( V_o \) is Invariant.

Fig 8. \( V_o \) is invariant \( D = 15\%, R = 10\Omega \)

5. Results Analysis

The curve reflects the relationship between critical inductor average current and duty cycle: According to the following formula [3]:

\[
I_{LB} = \frac{T V_d}{2L} D(1 - D)
\]

(3)

\[
I_{LB,\text{max}} = \frac{T S V_d}{8L}
\]

(4)

I get the following equation:

\[
I_{BL} = 26.67 D(1 - D)
\]

(5)

\[
I_{LB,\text{max}} = 6.67
\]

Fig 9. Relationship between average current and duty cycle of critical inductance
6. Conclusion

a. In the case of continuous current, the output dc voltage is linearly with the switch duty cycle, and it is not related to other circuit parameters. Therefore, in the case of continuous current, the buck chopper can be regarded as the current transformer, and its equivalent ratio can be adjusted by controlling the switch duty cycle between 0 and 1[4].

b. In the discontinuous current mode, there are two conditions: 1) is invariant; 2) is invariant;
   (1) In the case of is invariant, other parameters remain their value. When the power of output load is decreasing, in other words, the load resistance is increasing, the average inductance current will decrease, the inductance current is discontinuous.
   (2) In the case of is invariant, adjust duty cycle. When the actual duty cycle is smaller than the duty cycle of critical condition, the inductance current is discontinuous.

References