

- Mobile Robots", *Int. Journal of Engineering Research and Applications*, **1**(4) (2011), pp.1262-1267
24. E. Bonabeau, M. Dorigo and G. Theraulaz, *Swarm Intelligence: From Natural to Artificial Systems.*, (NY: Oxford University Press, New York, 1999)
 25. M. Dorigo, G. Di Caro and L. M. Gambardella, Ant algorithms for discrete optimization, *Artificial Life*, **5**(2) (1999) pp. 137-172
 26. K. Konolige, K. Myers, E. Ruspini, The Saphira Architecture: A Design for Autonomy, *Journal of Experimental and Theoretical Artificial Intelligence* **9** (1997), pp. 215-235
 27. A. Oreback, H. I. Christensen, Evaluation of Architectures for Mobile Robotics, *Autonomous Robots*, **14**(1) (2003), pp. 33–49
 28. A. Saffiotti, K. Konolige, and E. H. Ruspini, A Multivalued Logic Approach to Integrating Planning and Control, *Artificial Intelligence* **76**(1-2), 1995.
 29. J. Connell, SSS: A Hybrid Architecture Applied to Robot Navigation, *In the Proc. of the IEEE Conference on Robotics and Automation*, (Nice, France, 1992), pp. 2719 - 2724
 30. K. Konolidge, COLBERT: A language for reactive control in Saphira. *In the Proc. of German Conference on Artificial Intelligence*, (Freiburg, Germany, 1997), pp. 31-52
 31. N. J. Nilsson, Teleo-Reactive Programs for Agent Control, *Journal of Artificial Intelligence Research Vol. 1*, 1994