

Iterative migration of gravity and gravity gradiometry data at Bathurst Mining Camp

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Three-dimensional (3D) inversion of full tensor gradiometry (FTG) data continues to be an active area of research and development. We have recently developed a method of potential field migration, which extends to the case of the potential field the general principles of seismic and electromagnetic migration. This new approach provides a rapid method for direct transformation of observed gravity and gravity gradient data into spatial distributions of density. We demonstrate in this paper that migration can be applied iteratively to get more accurate subsurface distributions of the physical properties of rocks. We show that, the iterative migration is practically equivalent to the basic gradient-type inversion algorithms with one very important difference: the gradient directions on each iteration are determined by migration of the corresponding gravity, and gravity gradient data. This is significant because the last transformation is very well developed in the theory of potential field interpretation. In other words, the iterative migration makes it possible to use the powerful and stable technique of upward continuation for the solution of the inverse problem. We present a model study and a case study for the 3D iterative imaging of FTG data from New Brunswick, Canada.

Keywords—migration; gravity gradiometry; imaging; inversion

I. INTRODUCTION

Density distribution provides important geophysical information that helps in regional geological studies and mineral and energy resource exploration. In oil and gas exploration, density distribution is used to reduce the non-uniqueness of recovering 3D velocity models from an acoustic impedance. In mineral exploration, density and magnetic susceptibility models are used to locate mineralization zones. At the same time, determining 3D density distribution from gravity and/or gravity gradiometry data is a very challenging problem. Until recently, iterative 3D inversion of gravity and gravity gradiometry data to 3D density models was the only practical tool for quantitative interpretation. A number of publications have discussed 3D inversion with smooth (e.g., Li ^[1]) or focusing (e.g., Zhdanov et al. ^[2]) regularization. However, an interpretation workflow including 3D inversion could be complicated and time consuming and it is very dependent on the a priori model and constraints used.

In this paper, we develop a novel approach, which is based on the ideas of potential field migration as originally

introduced by Zhdanov ^[3]. The principles of this approach were presented in Wan and Zhdanov ^[4], where it was demonstrated that migration could be described by an action of the adjoint operator on the observed data. When applied to potential fields, migration manifests itself as a special form of downward continuation of the potential field and/or its gradients, which is obtained by relocating the sources of the observed field into the upper half-space as mirror images of the true sources. Contrary to conventional downward continuation of the potential field, downward continuation of the migration field is away from the mirror images of the sources. Therefore, migration is a stable transform, similar to upward continuation. By analogy to iterative electromagnetic migration (e.g., Mehanee and Zhdanov ^[5], Zhdanov ^[3][6][7], Zhdanov and Ueda ^[8]), the adjoint operators may be applied iteratively, which results in the iterative migration method. We present a model study and a case study for the 3D iterative migration of the FTG marine gravity gradiometry data from New Brunswick, Canada.

II. GRAVITY GRADIOMETRY DATA AND MIGRATION DENSITY

The gravity field, g , can be expressed by the gravity potential $U(\mathbf{r})$:

$$\mathbf{g}(\mathbf{r}) = \nabla U(\mathbf{r})$$

$$U(\mathbf{r}) = \gamma \iiint_D \rho(\mathbf{r}') \frac{\mathbf{r}' - \mathbf{r}}{|\mathbf{r}' - \mathbf{r}|^2} dV' \quad (1)$$

where γ is the universal gravitational constant ($\gamma = 6.67384 \times 10^{-11} \text{ m}^3/\text{kgs}^2$) and ρ is the anomalous density distribution within a domain D , where integration is conducted over the variable \mathbf{r}' .

The second spatial derivatives of the gravity potential $U(\mathbf{r})$,

$$\mathbf{g}_{\alpha\beta} = \frac{\partial^2 U(\mathbf{r})}{\partial \alpha \partial \beta}, \quad \alpha, \beta = x, y, z \quad (2)$$

form a symmetric gravity tensor:

$$\mathbf{g} = \begin{vmatrix} g_{xx} & g_{xy} & g_{xz} \\ g_{yx} & g_{yy} & g_{yz} \\ g_{zx} & g_{zy} & g_{zz} \end{vmatrix} \quad (3)$$

The expressions for the gravity tensor components can be calculated based on equations (1) and (2):

$$g_{\alpha\beta} = \gamma \iiint_D \frac{\rho(\mathbf{r}')}{|\mathbf{r}' - \mathbf{r}|^3} K_{\alpha\beta}(\mathbf{r}' - \mathbf{r}) d\mathbf{v}' \quad (4)$$

where the kernels, $K_{\alpha\beta}$, are equal to

$$K_{\alpha\beta}(\mathbf{r}' - \mathbf{r}) = \begin{cases} 3 \frac{(\alpha - \alpha')}{|\mathbf{r}' - \mathbf{r}|^2}, & \alpha \neq \beta \\ 3 \frac{(\alpha - \omega)^2}{|\mathbf{r}' - \mathbf{r}|^2} - 1, & \alpha = \beta \end{cases}, \quad \alpha, \beta = x, y, z \quad (5)$$

Following Zhdanov^[3] and Wan and Zhdanov^[4], the migration density $\rho_{\alpha\beta}^m$ can be calculated from the migration gravity field, $g_{\alpha\beta}^m(\mathbf{r})$, as follows

$$\begin{aligned} \rho_{\alpha\beta}^m(\mathbf{r}) &= k_{\alpha\beta} \omega_{\alpha\beta}^{-2}(z) g_{\alpha\beta}^m(\mathbf{r}) \\ &= k_{\alpha\beta} \omega_{\alpha\beta}^{-2}(z) \gamma \iint_s \frac{g_{\alpha\beta}(\mathbf{r}) - g_{\alpha\beta}^{obs}(\mathbf{r})}{|\mathbf{r}' - \mathbf{r}|^3} K_{\alpha\beta}(\mathbf{r}' - \mathbf{r}) ds \quad (6) \end{aligned}$$

where unknown coefficient $k_{\alpha\beta}$ can be determined by a linear

line search, and the linear weighting operator $\omega_{\alpha\beta}$ is calculated by the square root of the integrated sensitivity of the gravity gradient field (Wan and Zhdanov^[4]).

III. ITERATIVE MIGRATION

The equation (6) can produce a migration image of density distribution in the lower half-space. A better quality migration image can be produced by repeating the migration process iteratively. We begin with the migration of the observed gravity and/or gravity tensor field data to get the density distribution. In order to check the accuracy of our migration imaging, we apply the forward modeling and compute a residual between the observed and predicted data for the given density model. If the residual is smaller than the prescribed accuracy level, we use the migration image as a final density model. In a case where the residual is not small enough, we migrate the residual field and produce the density, $\delta\rho_1^m$, to the original density model using the same analysis which we have applied to the original migration:

$$\rho_2^m = \rho_1^m - \delta\rho_1^m == \rho_1 - k_1(W_m^* W_m)^{-1} l_1 \quad (7)$$

where $\delta\rho_1^m$ stands for the migration image obtained by the residual field migration, equation (6).

A general scheme for iterative migration can be described by the following formula:

$$\rho_{n+1}^m = \rho_n^m - \delta\rho_n^m == \rho_n - k_n(W_m^* W_m)^{-1} l_n \quad (8)$$

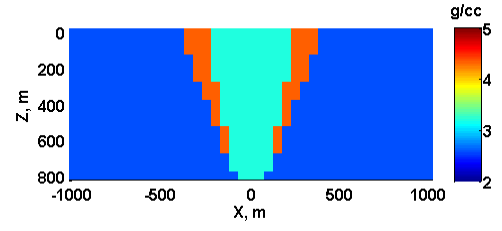


Fig.1 Vertical cross section of the density model.

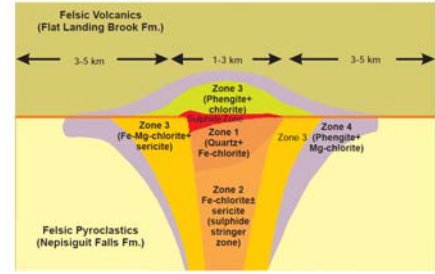


Fig.2 A schematic composite section through a VMS alteration system in the Bathurst camp as an example of a VMS proximal alteration zone metamorphosed to greenschist-grade mineral assemblages. From Goodfellow et al. (2003).

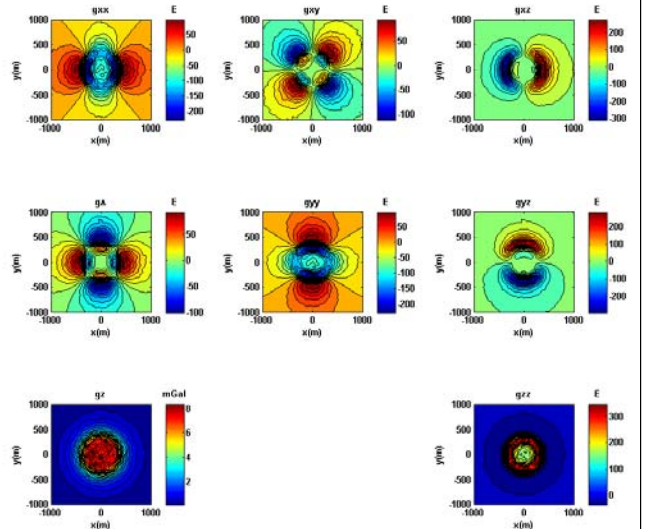


Fig.3 Synthetic gravity and gravity gradient data for VMS deposit model.

where l_n is a gradient direction on the nth iteration, computed using the following integral

$$l_n(\rho) = \gamma \iint_s \frac{g_{\alpha\beta}(\mathbf{r}) - g_{\alpha\beta}^{obs}(\mathbf{r})}{|\mathbf{r}' - \mathbf{r}|^3} K_{\alpha\beta}(\mathbf{r}' - \mathbf{r}) ds \quad (9)$$

where $g_{\alpha\beta}^n(\mathbf{r})$ are the predicted gravity gradient fields on the n th iteration.

The iterative migration is terminated when the residual field becomes smaller than the required accuracy level of the data fitting.

Similar to iterative inversion, iterative migration can be implemented with regularization (Zhdanov [3]). This also allows us to apply both the smooth and focusing stabilizers expressions (Wan and Zhdanov [4]).

IV. MODEL STUDY

We have examined the effectiveness of the iterative migration using synthetic gravity and gravity gradiometry data computed for a simple model, shown in Figures 1. The model represents a simplified model of volcanogenic massive sulfide (VMS) deposits (see Fig.2). It has three different density values, from the center to outside: 3.2 g/cm³ (felsic), 4.3 g/cm³

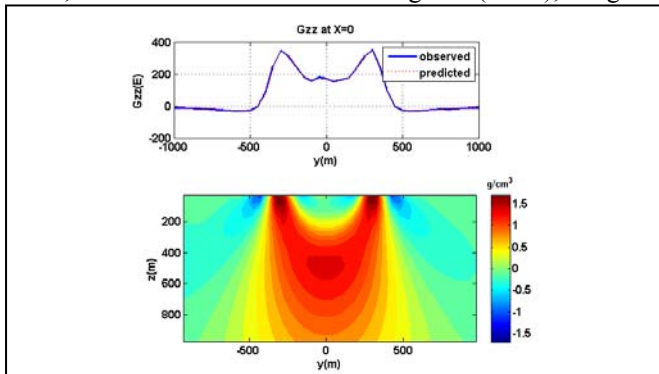


Fig.4 Results of iterative migration with smooth stabilizer for g_{zz} component. The bottom panel shows the migration density distribution in the center cross section, while the top panel presents the profiles of the observed and predicted data.

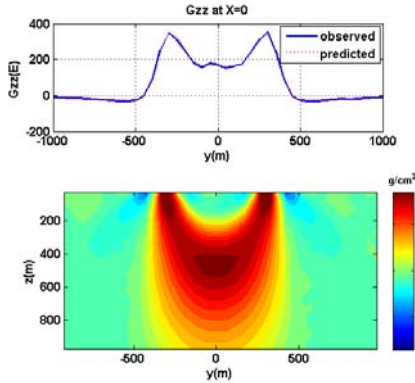


Fig.5 Results of iterative migration with focusing stabilizer for g_{zz} component. The bottom panel shows the migration density distribution in the center cross section, while the top panel presents the profiles of the observed and predicted data.

(mafic), and 2.6 g/cm³ (host rock), respectively. Figures 1 show the center cross section of the model. The observation surface is located 80 m above the ground. The survey area

extends from -1000 m to 1000 m along the x direction and from -1000 m to 1000 m along the y direction. There are 41 x 41 = 1681 data points for each component. For testing the algorithm, the synthetic observed data generated for this model were contaminated by 5% random noise.

Fig.3 shows the synthetic observed data computer simulated for this model. One can see that the anomaly is affected by the noise and becomes asymmetric.

The migration domain was selected from -1000 m to 1000 m in the x direction, from -1000 m to 1000 m in the y direction, and from 0 m to 1000 m in the z direction.

We have applied the iterative migration with the smooth stabilizer to all of components. The bottom panel in Fig.4 shows the migration density distribution in the center cross section for g_{zz} component, while the top panel presents the profiles of the observed and predicted data. One can see that the migration result locates the target and the data fitting is very good.

We have also applied iterative migration with focusing stabilizer. Fig.5 shows the migration density distribution in the center cross section, obtained by iterative migration with focusing stabilizer for g_{zz} component. One can see that the iterative migration with focusing stabilizer recovers the true density value of the target.

Case study: FTG survey from New Brunswick, Canada

We illustrate our method with an example from the Bathurst Mining Camp in New Brunswick, Canada, where at least 35 Pb-Zn-Cu-Ag type VMS deposits and over 100 known mineral occurrences have been discovered since the early 1950s.

The structural geology of the camp is complex, with five groups of folds identified. It has been suggested that most of the Tetagouche volcanic rocks are of basin-margin origin, deposited on a rifting continental crust. It follows that many of the VMS deposits are associated with tuffite and silicic volcanic rocks of the Nepisiguit Falls and Flat Landing Brook formations of the Tetagouche Group (Van Staal [5], Lentz [6]). Typically, the VMS deposits have a density of about 4 g/cc, whereas the host rocks (sediments, felsic tuffs, or their metamorphic equivalents) have densities between 2.7 and 2.8 g/cc (Dransfield et al [7]).

On behalf of Noranda (now Glencore), SLAM Exploration, and the Government of New Brunswick, Bell Geospace acquired 15,500 line km of Air-FTG full tensor gravity gradiometry data that covered more than 2,755 square km of the camp during 2004. The survey was flown at 200 m line spacing with 2000 m tie lines and 80 m topographic drape. Bell Geospace subsequently re-processed the Air-FTG data during 2010 using improved terrain correction, leveling, automatic tilt and full tensor noise reduction (FTNR). Figure 19 shows the Air-FTG full tensor gradient data collected in 2004 with the terrain corrections applied.

