Abstract—The bulb bow of bulk carrier and the double hull oil tanker are simulated. Based on the numerical software ANSYS/LS-DYNA, quantitative analysis was performed for these types of ship side collision. By the results of simulation, the critical velocities lead crack both on outer-plate and inner-plate of collided ship are obtained, by numerically analyzing the relations between the critical velocity and the tonnage of the collided ships, and the mathematical expressions are developed, which can provide suggesting for maritime management.

Keywords- ship collision; numerical simulation; ship tonnage; critical velocity; numerical analysis

I. INTRODUCTION

With the development of shipping, maritime traffic accidents often occurs. The ship collision has occupied a large proportion in the maritime traffic accidents, which is one of the important research field of shipping industry concerned, therefore many researchers were studied in the filed [1-7]. Ship collision will cause serious impact on marine environment. Study ship collision in order to improve the crash worthiness and reduce the consequences.

Double hull oil tanker outer or inner shell rupture is a serious failure caused by the ship collision. When processing of the simulation results revealed that there exists a critical velocity for the struck ship, if the striking ship collide the struck ship velocity exceeds the critical velocity, the struck ship’s outer or inner shell will rupture. Therefore, determine the critical velocity of the striking ship is an important and meaningful research. Based on the numerical software ANSYS/LS-DYNA, quantitative analysis was performed for ship side collision, and to determine the cause of the relationship between the critical velocity and the ship tonnage according to the simulation results.

II. SELECT TARGET SHIP TYPE

According to the Ministry of Transportation's Maritime Administration of the ship accident statistics [8], more than 100,000-ton vessel encounter with the same tonnage and above-ton ship is less likely, the number of ship collision accidents are less. Taking into account the tanker was collide and leaked, the impact on the marine environment of the largest, and extensive bulk cargo ship tonnage distribution. Taken together, the paper selected the striking ship are the bulk cargo ship, and the struck ship are the double hull oil tanker. Meanwhile, according to the requirements of MARPOL Convention and China Classification Society Rules for Seagoing Steel Ships and other regulations, taking into account the modeling and simple calculations, checking the vertical actual ship data, based on the results of the selected summary ship's main dimensions and main parameters are shown in Table III.

III. COLLISION SCHEMATIC AND FINITE ELEMENT MODELING

Ship collision is an extremely complex nonlinear dynamic response process, and have many factors [9,10]. This article only demonstrates the influence of the tonnage on critical velocity, and assuming the striking ship that have a prominent bulb (other bow types will be studied in another paper) perpendicular to the collide the struck ship that is quiescent, and keep the impact position remain unchanged.

The striking ship adopt elastic-plastic material and sheet thickness consistent with reality, and set the internal components. To ensure the quality of the striking ship, the actual center of gravity is consistent with an increase in the rear side of the bow cabin quality as an accessory structure [11-14], by changing the quality of the attachment structure to change the ship’s tonnage, the struck ship’s plate thickness and other related components according to the actual structure and material properties. And ensure the struck ship's quality, consistent with the actual center of gravity, etc. Cabin structure using plastic dynamic model simulations. Finite element model shown in Figure 1.

According to relevant research, additional water quality could solution the effect between the ship body and the fluid. Using SHELL unit to simulate the ship collision, and the collide area mesh refinement, material model....
considering strain rate sensitivity of using Cowper-Symonds constitutive equation, failure strain is taken as 0.1\cite{15,16}. Take the master-slave contact algorithm of structure involved in the collision, and the struck ship side structure is the definition of automatic single surface contact.

Since the \( V_{\text{outside}} \) must have some relation with the tonnage of striking ship (\( M_{\text{striking}} \)), and therefore the parameter \( C \) and the \( M_{\text{striking}} \) were fitted, shown in Figure 3, and the relationship between parameter \( C \) and \( M_{\text{striking}} \) can be expressed as follows:

\[
C=44.37\cdot M_{\text{striking}}^{-0.08}
\]

In conclusion, the relationship between critical velocity of outer shell and tonnage of the collision ship can be expressed as:

\[
V_{\text{outer}}=44.37\cdot M_{\text{striking}}^{-0.08}-1.302\cdot \ln M_{\text{struck}}
\]  

(2)

C. The relationship between critical velocity of inner shell and tonnage of the collision ship

The relationship between critical velocity of inner shell and tonnage of the collision ship is shown in Figure 4. Similarly, the relationship can be expressed as follows:

\[
V_{\text{inner}}=40.77\cdot M_{\text{striking}}^{-0.07}-\ln M_{\text{struck}}
\]

(3)

Table on the simulation results showed that: \( V_{\text{outer}} \) and \( V_{\text{inner}} \) are inverse with \( M_{\text{striking}} \) and \( M_{\text{struck}} \), and the drift velocity is inverse with \( M_{\text{struck}} \). It is analyzed that the ship drift velocity will affect the \( V_{\text{outer}} \) and \( V_{\text{inner}} \).

Therefore, this paper designed two experiments to verify the above two cases:

(1) 100,000-ton ship at a velocity of 6m/s vertical collide with the different tonnage of struck ship;

(2) 100,000-ton ship at a velocity of 5m/s respectively vertically collide the 50,000-ton double-hull oil tanker which the cargo is constrained and the other is without constrained.
Figure 4. Curvilinear relation between $V_{\text{outer}}$ and $M_{\text{striking}}$ and $M_{\text{struck}}$

Figure 5. Drift velocity of the collided ship

The one case simulation results can be shown in Figure 5, we can see, the smaller of $M_{\text{struck}}$, the greater of the drift velocity, that’s the reason of $V_{\text{outer}}$ and $V_{\text{inner}}$ are inverse with $M_{\text{struck}}$.

Compared two kinds of collision force generated by the second case, as shown in Figure 6, can be seen from the figure:

1. The collision force curve had two obvious unloading when the cargo was constrained, which represent the inner and outer shell rupture; however, when the cargo without constrained, the collision force curve only had one unloading, which represent the outer shell rupture.

2. When the cargo was constrained that the time of the outer shell rupture was earlier than the cargo without constrained.

3. When the cargo was constrained that the collision force was larger than the cargo without constrained, therefore the drift velocity of the struck ship which could “reduce” the collision force.

Figure 7 shows the damage of the inner shell, from the figure when the cargo was constrained the inner shell was ruptured, and when the cargo without constrained the inner shell only had buckling deformation but not broken, which also proves the above conclusions.

V. CONCLUSIONS

(1) The function of outer shell critical velocity of the striking ship is $V_{\text{outer}}=44.37\times M_{\text{striking}}^{0.08} - 1.302 \times \ln M_{\text{struck}}$; and the function of inner critical velocity of the striking ship is $V_{\text{inner}}=40.77\times M_{\text{striking}}^{0.07} - \ln M_{\text{struck}}$.

(2) The tonnage of striking ship is inversely with $V_{\text{outer}}$ and $V_{\text{inner}}$, which means the striking ship tonnage is larger than the critical velocity is smaller.

(3) The tonnage of struck ship is inversely with $V_{\text{outer}}$ and $V_{\text{inner}}$, which means the struck ship tonnage is lighter than the critical velocity is bigger, the reason is that the struck ship tonnage is lighter that the drift velocity is bigger.

(4) Through this study, it can provide the theoretical basis for effective maritime control, control of the ship velocity in specific waters, to avoid oil tanker collision which may lead oil spill. In addition, for large oil tankers, we should pay more attention to supervision.
TABLE III. MAIN DIMENSIONS AND PARAMETERS

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<tr>
<th>Ship type</th>
<th>Length</th>
<th>Breadth</th>
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<th>Distance of</th>
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<th>Thickness of</th>
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<td>13.8</td>
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REFERENCES