The Stability analysis for a kind of Impulsive Hopfield cellular neural networks

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Abstract. As an important tool to study practical problems of biology, engineering and image processing, the cellular neural networks (CNNs) has caused more and more attention. In this paper, by means of iterative analysis, the existence of periodic solution and the uniform stability of the equilibrium point of Hopfield cellular neural networks with impulsive effects are considered. Some new results are obtained.

Introduction

Cellular neural networks (CNNs) is formed by many units called cells, the structure of the CNN is similar to that found in cellular automata, namely, any cell in a cellular neural network is connected only to its neighbor cells. A cell contains linear and non-linear circuit elements, which typically are linear capacitors, linear resistors, linear and nonlinear controlled sources, and independent sources. The circuit diagram and connection pattern modelling a CNN can be found in [1,2]. Recently, due to the CNNs applicability in image and signal processing, vision, pattern recognition and optimization, which have been paid much attention. Extraordinarily, the stability and equilibrium properties of cellular neural networks introduced in [3] have been investigated by many researches [4-6] where most of the results derive the conditions for uniqueness and global asymptotic stability of the equilibrium point for CNNs.

In this paper, we are concerned with the existence of periodic solution and the uniform stability of the equilibrium point for Hopfield CNNs with impulsive effects. Different from most of the existing methods, we employ the iterative analysis method. Several previous results are improved and generalized.

Preliminaries

In this paper, we consider the following Hopfield CNNs with impulsive effects:

\[
\begin{align*}
\frac{dx_i(t)}{dt} &= -\frac{x_i(t)}{R_i} + \sum_{j=1}^{N} a_{ij} f_j (x_j(t)) + J_i, \quad t \in J_i, \\
\Delta x_i (t_k) &= x_i (t_k^-) - x_i (t_k^+) = H_{ik} x_i (t_k^+), \quad t = t_k, \\
x_i (t) &= \varphi_i (t), \quad t \in (-\infty, 0],
\end{align*}
\]

where \( a_{ij} \in \mathbb{R}, i, j = 1, 2, \ldots, n, J = [0, +\infty), \ 0 = t_0 < t_1 < t_2 < L, \ J' = J - \{t_1, t_2, \ldots\}, \ H_{ik} \in C (\mathbb{R}, \mathbb{R}), \)
\[ k \in \mathbb{Z}^+, \lim_{k \to \infty} t_k = \infty, \varphi_i(t) \] is a real-valued continuous function defined on \((\infty,0]\). The positive constants \(C_i\) and \(R_i\) are the neuron amplifier input capacitance and resistance, respectively; \(J_i\) is the constant input from outside of the network, \(n\) denotes the number of units in a neural network, \(x_i(t)\) denotes the state of the \(i\)th unit at time \(t\) and is a continuous \(T\)-periodic function, \(f_j(x_j(t))\) denotes the output of the \(j\)th unit at time \(t\), \(a_{ij}\) denotes the strength of the \(j\)th unit on the \(i\)th unit at time \(t\), \(\Delta x_i(t_k)\) corresponds to the abrupt changes of the state at fixed impulsive moment \(t_k\).

Let \(J_1 = [0,T], J_1 \cap t_k = \{t_1, t_2, \ldots, t_p\}, PC(J_1, R) = \{x_i : J_1 \to \mathbb{R}; x_i(t)\) is continuous everywhere except for some \(t_k\) at which \(x_i(t^+_k)\) and \(x_i(t^-_k)\) exist and \(x_i(t^-_k) = x_i(t^+_k), k = 1,2, \ldots, p\}.\) With norm \(\|x\|_p = \sup\{|x_i(t)| : t \in J_1\},\) then \(P\) is a Banach space.

We call constant vector \(x^* = (x^*_1, x^*_2, \ldots, x^*_n)^T\) as the equilibrium point of system (2.1), if it satisfies the following equation:

\[
\begin{align*}
\frac{1}{R_i} x^*_i = \sum_{j=1}^{n} a_{ij} f_j(x^*_j) + J_i, & \quad t \neq t_k, \\
H_{ik}(x^*_i) = 0, & \quad t = t_k.
\end{align*}
\]

In this paper, we assume that some conditions are satisfied so that the equilibrium point of system (2.1) does exist.

In order to prove the stability of the equilibrium point of system (2.1), we just need to prove the stability of zero solution of following system:

\[
\begin{align*}
 C_j y_j(t) = -\frac{y_j(t)}{R_j} + \sum_{j=1}^{n} a_{ij} g_j(y_j(t)), & \quad t \in J^*, \\
\Delta y_j(t_k) = G_{ik}(y_j(t_k)), & \quad t = t_k, \\
y_j(t) = \phi_j(t), & \quad t \in (-\infty,0].
\end{align*}
\]

where \(g_j(y_j(t)) = f_j(y_j(t) + x^*_j) - f_j(x^*_j), G_{ik}(y_j(t_k)) = H_{ik}(y_j(t_k) + x^*_j), \phi_j(t) = \phi_j(t) - x^*_j.\) Let

\[
\|\Phi\| = \max \left\{ \sup_{t \in (-\infty,0]} |\phi_j(t)|, i = 1,2, \ldots, n \right\}, \quad \|y\| = \max \left\{ \sup_{t \in (-\infty,0]} |y_i(t)|, i = 1,2, \ldots, n \right\}.
\]

**Definition** A piecewise continuous function \(x(t) \in P_o : [0,T] \to \mathbb{R}^n\) is called a \(T\)-periodic solution of Eq.(2.1), if

1. \(x(t)\) satisfies Eq.(2.1) for \(t \in (-\infty,T]\);
2. \(x(t) = x(t+T)\) for \(t \in \mathbb{R}^+\);
(3) \( x(t) \) is continuous at \( t \neq t_k, x(t_k) = x(t_k^+) \), and \( x(t_k^-) \) exist for \( \forall t_k \in J_1 \cap \{ t_k \} \).

The following are the basic hypotheses:

\( (H_1) \) There exist constants \( L_i > 0 \) such that \( |f_i(x_1) - f_i(x_2)| \leq L_i |x_1 - x_2| \);

\( (H_2) \) There exist constants \( q_{ik} > 0 \) such that \( |H_{ik}(x_1) - H_{ik}(x_2)| \leq q_{ik} |x_1 - x_2| \);

We denote:

\[
T = \max \{ \{ a_i \} \}, \quad D_i = T \varepsilon_i, \quad D^* = \max \{ D_i \}, \quad Q_i = \sum_{k=1}^{n} q_{ik}
\]

\[
F = \min_{j=1, \varepsilon_i} \left\{ \left( 1 - e^{-\frac{1}{\varepsilon_i^{\varepsilon_i}}} \right) C_i \right\}, \quad A = \max_{i=1, \varepsilon_i} \left\{ \frac{\sum_{j=1}^{n} a_j |D^*| + Q_i C_i}{1 - e^{-\frac{1}{\varepsilon_i^{\varepsilon_i}}} C_i} \right\}, \quad D = \max_{i=1, \varepsilon_i} \left\{ \sum_{j=1}^{n} a_j |D^*| \right\}
\]

\( (H_3) \) \( 0 < A < 1, \quad 0 < \frac{naD^*}{F} < 1 \).

**Lemma 2.1** Let \( y(t) = [y_1(t), y_2(t)] \) be a \( T \)-periodic solution of Eq. (2.2), then it can be presented as

\[
y_j(t) = \int_{0}^{t} g_j(t,s) \sum_{j=1}^{n} a_j g_j(y_j(s)) \, ds + \sum_{k=1}^{n} g_j(t,t_k) G_{ik}(y_j(t_k)), \quad t \in J_1,
\]

where

\[
g_j(t,s) = \begin{cases} \frac{e^{t-s}}{C_i}, & 0 \leq s \leq t \leq T, \\ \frac{e^{-t+s}}{e^{t-s}} & 0 \leq t < s \leq T. \end{cases} \quad i = 1, 2, \varepsilon_i.
\]

**Main results**

**Theorem 3.1** Suppose that hypotheses \( (H_1)-(H_3) \) hold, then the problem (2.2) has a unique \( T \)-periodic solution \( y(t) = [y_1(t), y_2(t)] \) on \([0, T]\), and

\[
\|y_i\| \leq \frac{2D}{1-A} \|\Phi\|, \quad i = 1, 2, \varepsilon_i.
\]

**Proof.** We define the iteration

\[
y_i^{(m)}(t) = \begin{cases} \int_{0}^{t} g_j(t,s) \sum_{j=1}^{n} a_j g_j(y_j^{(m-1)}(s)) \, ds + \sum_{k=1}^{n} g_j(t,t_k) G_{ik}(y_j^{(m-1)}(t_k)), & t \in J_1, \\ \|\Phi\|, & t \in (-\infty, 0]. \end{cases}
\]
\[
\begin{align*}
y_i^{(0)}(t) &= \begin{cases} 
\int_0^t \frac{g_i(t,s)}{C_i} \sum_{j=1}^{n_i} a_{ij} g_j(y_j(0))\,ds, & t \in J, \\
\Phi &\quad t \in (-\infty, 0].
\end{cases}
\end{align*}
\]
\[
\|y_i^{(1)}(t) - y_i^{(0)}(t)\| \leq \int_0^t \left| \frac{g_i(t,s)}{C_i} \sum_{j=1}^{n_i} a_{ij} \left| y_j^{(0)}(s) - y_j(0) \right| ds + \sum_{k=1}^{n} q_{ik} \left\| g_i(t,t_k) \right\| \left\| y_i^{(0)}(t_k) \right\|.
\]
\[
\left\| y_i^{(1)} - y_i^{(0)} \right\|_p \leq \frac{D\|\Phi\| + \Phi}{1 - e^{-\frac{t}{c_i}}} \sum_{j=1}^{n_i} \left| a_{ij} \right| D^+ + \frac{Q_i D\|\Phi\|}{1 - e^{-\frac{t}{c_i}}} \leq (A + 1) D\|\Phi\|.
\]
\[
\left\| y_i^{(2)} - y_i^{(1)} \right\|_p \leq A(A + 1) D\|\Phi\|, \quad \left\| y_i^{(3)} - y_i^{(2)} \right\|_p \leq A^2(A + 1) D\|\Phi\|.
\]

Again, using induction, we can get that
\[
\left\| y_i^{(m+1)} - y_i^{(m)} \right\|_p \leq A^m(A + 1) D\|\Phi\|, \quad m = 0, 1, \ldots, n.
\]
\[
\left\| y_i^{(m+1)} \right\|_p \leq \sum_{m=0}^{n} \left| y_i^{(m+1)}(t) - y_i^{(m)}(t) \right| + \left| y_i^{(0)}(t) \right| \leq \frac{2D\|\Phi\|}{1 - A}.
\]

For any \( p \in N, n + p \geq n, i = 1, 2, \ldots, n \), we have
\[
\left| y_i^{(m+p)}(t) - y_i^{(n)}(t) \right| \leq \frac{A^n}{1 - A}(1 + A) D\|\Phi\|.
\]

Therefore, the sequence \( \{ y_i^{(m)}(t) \} \) is uniformly convergent on \([0, T]\), let \( \lim_{m \to \infty} y_i^{(m)}(t) = y_i(t) \), obviously, \( y_i(t) \) is a \( T \)-periodic solution to the initial value problem (2.2), which satisfies the inequality (3.1). This completes the proof of Theorem 3.1.

**Theorem 3.2** Suppose that the hypotheses (H1)-(H3) hold, then the zero solution of the initial value problem (2.2) is uniformly stable.

**Theorem 3.3** Suppose that the hypotheses (H1)-(H3) hold, then the equilibrium point of the initial value problem (2.1) is uniformly stable.

**References**


