

Predictive Control System of Gas Recovery Based on Neural Network and Fuzzy Control

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Abstract-Aiming at the problem that the converter gas steam recovery and average recovery rate is less than forty percent in some steel factory, this research optimized recycle-using system of steel plant's converter gas by applying neural-network adaptive predictive control and fuzzy control. The simulation results showed that furnace gas emissions could reach $-5\sim 5L/h$, and the practice proved the average recovery of gas reached $97.5m^3/T$ after applying neural-network adaptive predictive control in practical application.

Keywords-predictive control system; gas recovery; neural-network; fuzzy control

I. INTRODUCTION

90-120 m³ gas can be recovered when per ton steel is made in the steel plant, the heating value of that gas reach about 1800~2000 kcal/m³, which is more than twice as high as the blast furnace gas heating and is secondary energy only less than the coke oven gas[1,2]. Take into account environmental protection and energy saving, the domestic large scale steel plants build almost gas recovery control system, but the recovery effect is not ideal[3]. Therefore, it is necessary for the steel plants to establish gas recovery control system.

Gas recovery systems of the steel mills have large delay, nonlinear and uncertainty features[4], it is very difficult to describe accurately the thermal process and implement the overall optimization by applying the traditional dynamic mathematical model control method[5,6], therefore, it is very necessary apply the advanced control method to the gas recovery system.

Aiming at the problem that the converter gas steam recovery and average recovery rate is less than forty percent in a certain steel factory, this research optimized recycle-using system of steel plant's converter gas by applying neural-network adaptive predictive control and fuzzy control.

II. GAS RECOVERY SYSTEM AND CONTROL STRATEGIES SITUATION IN A CERTAIN STEEL PLANT

A. The Principle of Gas Recovery System

The principle diagram of gas recovery system in a steel plant is shown in figure 1. Where 1 is the open hearth furnace, 2 is micro different pressure of the open hearth furnace, 3 is pre-washing tower, 4 is overflow entrance flow amount, 5 is RS entrance gas temperature, 6 is RS entrance pressure, 7 is

entrance flow of pre-washing tower, 8 is tension weight displacement, 9 is tension weight, 10 is controller signals, 11 is controller, 12 is uplink signals, 13 is downlink signals, 14 is proportional valve, 15 is cylinder, 16 is the outlet pressure of RS, 17 is dewatering device.

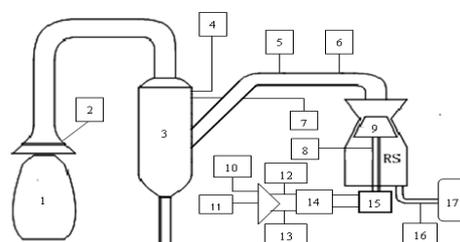


FIGURE 1. THE PRINCIPLE DIAGRAM OF GAS RECOVERY SYSTEM.

The principle of gas recovery can be understood from figure 1. Blast furnace gas passes pre-washing tower and RS after it is overflowed from the open hearth furnace mouth, which can be recovered and utilized after passing the dehydrator. The washing tower is mainly to remove the dust of the coal gas; RS controls mainly the flow of the coal gas. The throat mouth of RS becomes small, the wind resistance is increased and the gas flow becomes smaller when the tension weight goes up; On the contrary, gas flow becomes large. The tension weight needs to go down in order to expand the opening amount of the throat mouth, increase the gas flow and prevent the coal gas of the open hearth furnace mouth overflowing to the factory when the amount of overflow from the coal gas of the open hearth furnace mouth is larger. The tension weight needs to go up in order to reduce the opening amount of the throat mouth, reduce the gas flow and prevent the excessive air and low concentration in the recovery gas when the amount of overflow from the coal gas of the open hearth furnace mouth is smaller.

B. Control Strategies of The Gas Recovery System At Present

The major control strategies of the gas recovery system in a steel plant at present are as follows[4-7]:

- (1) The tension weight is not action within two and a half minutes after the gas recovery system is opened;
- (2) A control period of the tension weight is three seconds, two seconds are running and a second is stop state;
- (3) The controller applies programmable logical controller;

(4) Micro differential pressure signal of the open hearth furnace mouth is the control signals of the tension weight, this is input signal of the controller;

(5) Control method uses proportion control.

The major problems of the gas recovery control strategies in a steel plant are as follows:

- (1) Average recovery rate of the gas recovery is less than forty percent;
- (2) The gas amount of overflowing to the plant is more, which leads to serious air pollution in workshop;
- (3) The air content of the recovered gas is much larger.

III. CONTROL STRATEGIES OF THE GAS RECOVERY SYSTEM BASED ON NEURAL NETWORK

A. Control Principles of The Gas Recovery System Based on Neural Network and Fuzzy Control

There are about 40 meters pipeline and pre-washing tower from the micro differential pressure gauge of the open hearth furnace mouth to RS, as is shown in figure 1. Gas recovery system has pure delay characteristics because of the compressible features of gas[8]; system response is slower for the pure delay system. Therefore, the advanced control technology must be applied to this kind system in order to improve the control precision of the system. Figure 2 is the control model schematic diagram of gas recovery system.

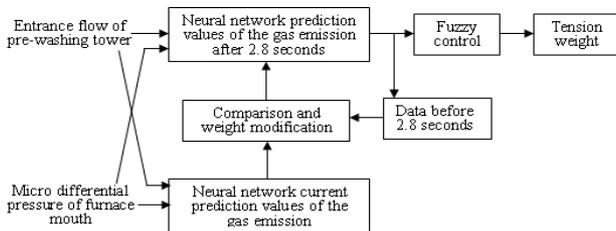


FIGURE 2. THE CONTROL MODEL SCHEMATIC DIAGRAM OF GAS RECOVERY SYSTEM.

Control principles in figure 2 are as follows: Input variables of the control system are entrance flow of pre-washing tower and micro differential pressure of the open hearth furnace mouth. Neural network is applied to estimate the gas emission current value and predict the gas emission value after 2.8 seconds at the open hearth furnace mouth, the two values are compared and then modify the weight of neural network; 2.8 seconds are a result of system identification by neural network. Gas emission amount is a key input variable of neural network and fuzzy control module. Tension weight is system actuator.

B. Adaptive Prediction Based on Neural Network

Neural network is applied to predict gas emission value of the open hearth furnace mouth because neural network has very good ability of nonlinear mapping[9]. Gas flow difference is ignored between the open hearth furnace mouth and pre-washing tower, the first ten measurement values of pre-washing tower entrance flow and micro differential pressure

at the open hearth furnace mouth are as input values of neural network. Because the system delay is about 2.8 seconds, so the prediction results are the gas emission amount of the open hearth furnace mouth after 2.8 seconds. Figure 3 is neural network model.

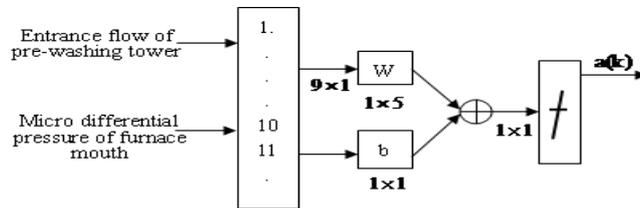


FIGURE 3. NEURAL NETWORK MODEL.

Decreasing gradient algorithm is adopted to adjust the weight value of neural network according to the measured data and the neural network model established, which makes the output values of neural network approach gas emission value $a(k)$ of the open hearth furnace mouth after 2.8 seconds.

C. Fuzzy Control Algorithm

It is very difficult to establish the precise mathematical model because gas recovery systems of steel plants have nonlinear and uncertainty. However, fuzzy control method does not need to build the mathematics model of the controlled object because it need only to set up a certain object mapping relationship according to the expert knowledge and experience[10]. Therefore, it is a better control method that fuzzy control and neural network are combined to achieve control of gas recovery system.

Fuzzy control linguistic variable of gas emission amount are as follows: the range of error e is $\{-20\text{Pa}, +10\text{Pa}\}$; The range of error changing rate E_c is $\{-20\text{Pa/s}, 20\text{Pa/s}\}$; The range of output U is $\{4\text{mA}, 25\text{mA}\}$. Fuzzy state of each linguistic variable is $\{NB, NM, NS, ZO, PS, PM, PB\}$. Control rules of the parameter U can be determined according to the parameter e and E_c . Control rules of parameter U is shown in Table 1.

TABLE I. CONTROL RULES OF U .

e	E_c						
	NB	NM	NS	ZO	PS	PM	PB
NB	PB	PB	PM	PM	PS	ZO	ZO
NM	PB	PM	PM	PS	PS	ZO	ZO
NS	PM	PM	PS	PS	ZO	NS	NM
ZO	PM	PS	PS	ZO	NS	NM	NM
PS	PS	PS	ZO	NS	NM	NM	PB
PM	ZO	ZO	NS	NM	NM	PB	PB
PB	ZO	ZO	NM	NM	PB	PB	PB

Fuzzy logic inference is finished by adopting min-max algorithm; Defuzzification is carried on by applying gravity method. Triangular membership function is selected for Variables e , E_c and U because it is more flexible than normal

distribution or Gauss type. Membership function of the parameters e , E_c and U are shown in figure 4.

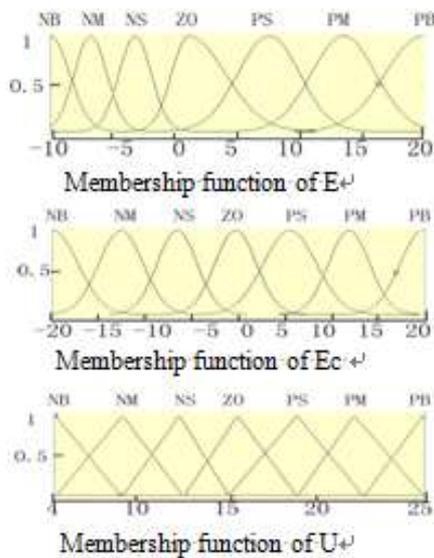


FIGURE 4. MEMBERSHIP FUNCTION OF E, EC AND U.

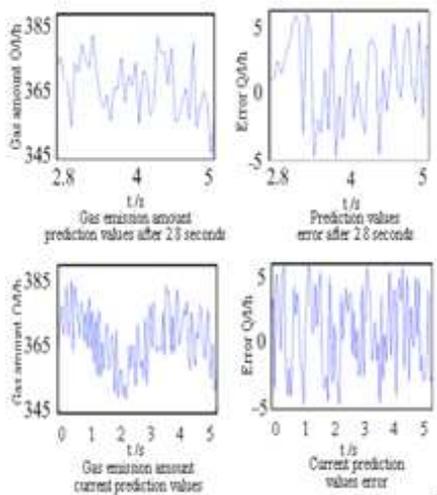


FIGURE 5. NEURAL NETWORK PREDICTION VALUES FOR GAS EMISSION AMOUNT AND ERROR.

IV. NEURAL NETWORK PREDICTION EFFECT OF GAS EMISSION AMOUNT OF THE OPEN HEARTH FURNACE MOUTH

Gas emission amount of the open hearth furnace mouth is system actual input variable, it is a key step for the control system to estimate the gas emission current value and predict the gas emission value after 2.8 seconds at the open hearth furnace mouth. Therefore, it is very necessary for neural network to test the prediction effect of gas emission amount at the open hearth furnace mouth. Test method is compared with the actual measured data and neural network prediction data. Figure 5

shows prediction values curve of gas emission amount and the error values curve between the actual measured values and neural network prediction values.

Current prediction values error and prediction values error after 2.8 seconds for gas emission amount at the open hearth furnace mouth are all between -5 and 5t/h, as is shown obviously in Figure 5. Results show that neural network prediction effect is quite ideal.

V. THE PRACTICAL APPLICATION EFFECT

Control method of gas recovery system adopt neural network and fuzzy control, neural network prediction and fuzzy operation are achieved by s7-300 controller. Control effect shows that gas recovery reach 97.5m³/T.

VI. CONCLUSION

This research analyzed in detail control strategies and problems of the gas recovery system at present, put forward a new control model of the gas recovery system based on neural network and fuzzy control, and optimized recycle-using system of steel plant's converter gas by applying this method. The simulation results showed that Current prediction values error and prediction values error after 2.8 seconds for gas emission amount at the open hearth furnace mouth are all between -5 and 5t/h, and the practice proved the average recovery of gas reached 97.5m³/T after applying neural-network adaptive predictive control in practical application.

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