

Symmetry Properties of Generalized Gas Dynamics Equations

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Abstract

We describe a class of generalized gas dynamics equations invariant under the extended Galilei algebra $A\tilde{G}(1, n)$.

Symmetry properties of the gas dynamics equations

$$\begin{cases} \vec{u}_0 + (\vec{u} \cdot \vec{\nabla})\vec{u} + \frac{1}{\rho}\vec{\nabla}p = 0, \\ \rho_0 + \operatorname{div}(\rho\vec{u}) = 0, \\ p = f(\rho), \end{cases} \quad (1)$$

where \vec{u} is the velocity, ρ is the density, p is the pressure of gas, were investigated in [1]. As has been shown in [1], the system (1) has the widest symmetry when $f(\rho) = \lambda\rho^{\frac{n+2}{n}}$ ($\lambda = \text{const}$, n is the quantity of space variables $\vec{x} \in R_n$). In this case a basis of the maximum invariant algebra of the equation (1) is represented by the operators

$$\begin{aligned} \partial_0, \quad \partial_a, \quad J_{ab} = x_a\partial_b - x_b\partial_a + u^a\partial_{u^b} - u^b\partial_{u^a}, \\ D_1 = x_0\partial_0 + x_a\partial_a, \quad D_2 = x_0\partial_0 - n\rho\partial_\rho - u^a\partial_{u^a}, \\ G_a = x_0\partial_a + \partial_{u^a}, \quad \Pi = x_0(x_0\partial_0 + x_a\partial_a - n\rho\partial_\rho - u^a\partial_{u^a}), \end{aligned} \quad (2)$$

where $a, b = \overline{1, n}$.

We shall call the algebra (2) the extended Galilean algebra and designate it by $A\tilde{G}(1, n)$. Other models of gas conduct are well-known except the system (1) (see, for example, [2]). Usually the first and second equations of the system (1) are invariables and the third equation has any form. For this reason we have the problem of finding the function

$$S = S(x_0, \vec{x}, \vec{u}, \rho, p, \vec{u}_0, \vec{u}_a, \rho_0, \rho_a, p_0, p_a), \quad (3)$$

where $a = \overline{1, n}$, $\vec{u}_a = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$, $\rho_a = \vec{\nabla}\rho$, $p_a = \vec{\nabla}p$, $\vec{u}_a = \frac{\partial\vec{u}}{\partial x_a}$, with which the system

$$\begin{cases} \vec{u}_0 + (\vec{u} \cdot \vec{\nabla})\vec{u} + \frac{1}{\rho}\vec{\nabla}p = 0, \\ \rho_0 + \operatorname{div}(\rho\vec{u}) = 0, \\ S = 0 \end{cases} \quad (4)$$

is invariant with respect to the algebra $AG\tilde{(1, n)}$. It follows from the invariance with respect to the operators ∂_0, ∂_a that this system has the form

$$\begin{cases} \vec{u}_0 + (\vec{u} \cdot \vec{\nabla})\vec{u} + \frac{1}{\rho}\vec{\nabla}p = 0, \\ \rho_0 + \text{div}(\rho\vec{u}) = 0, \\ \rho_0 + F(\vec{u}, \rho, p, \vec{u}_a, \rho_a, p_a) = 0. \end{cases} \tag{5}$$

The infinitesimal operator of the algebra $AG\tilde{(1, n)}$ has the following form

$$X = d_\mu\partial_\mu + c_{ab}J_{ab} + g_aG_a + \kappa_1D_1 + \kappa_2D_2 + a\Pi + \eta(x_0, \vec{x}, \vec{u}, \rho, p)\partial_\rho \tag{6}$$

Using invariance of the first equation of the system (5) with respect to the operator (6), we obtain

$$\eta = -(n + 2)(ax_0 + \kappa_2)p. \tag{7}$$

This means that all operators of the algebra (2) must have such a form except

$$D'_2 = D_2 - (n + 2)p\partial_p, \quad \Pi' = \Pi - (n + 2)x_0p\partial_p. \tag{8}$$

Demanding that the third equation of the system (5) be invariant with respect to the Galilean operators, we obtain

$$\frac{\partial F}{\partial u^a} = p_a. \tag{9}$$

Hence

$$F = (\vec{u}\vec{\nabla})p + \Phi(\rho, p, \vec{u}_a, \rho_a, p_a). \tag{10}$$

We assume that

$$\Phi = \Phi(\rho, p, \vec{\nabla}\vec{u}, \vec{\nabla}\rho, \vec{\nabla}p). \tag{11}$$

It follows from invariance with respect to the rotations J_{ab} that

$$\Phi = \Phi(\rho, p, w_1, w_2, w_3, w_4), \tag{12}$$

where

$$w_1 = \vec{\nabla}\vec{u}, w_2 = (\vec{\nabla}\rho)^2, w_3 = (\vec{\nabla}\rho)(\vec{\nabla}p), w_4 = (\vec{\nabla}p)^2. \tag{13}$$

Substituting (10)–(13) in the third equation of the system (5), we have

$$p_0 + (\vec{u} \cdot \vec{\nabla})p + \Phi(\rho, p, w_1, w_2, w_3, w_4) = 0. \tag{14}$$

Now let us consider the invariance of the equation (14) with respect to the operators D_1, D'_2, Π' . For each of them we obtain the equation for the function Φ

$$\begin{aligned} D_1 : & w_1\Phi_1 + 2w_2\Phi_2 + 2w_3\Phi_3 + 2w_4\Phi_4 - \Phi = 0, \\ D'_2 : & n\rho\Phi_\rho + (n + 2)p\Phi_p + w_1\Phi_1 + 2nw_2\Phi_2 + 2(n + 1)w_3\Phi_3 + \\ & 2(n + 2)w_4\Phi_4 - (n + 3)\Phi = 0; \\ \Pi' : & n\rho\Phi_\rho + (n + 2)p\Phi_p + 2w_1\Phi_1 + 2(n + 1)w_2\Phi_2 + 2(n + 2)w_3\Phi_3 + \\ & 2(n + 3)w_4\Phi_4 - (n + 4)\Phi + n\Phi_1 - (n + 2)p = 0. \end{aligned} \tag{15}$$

The function

$$\Phi = \frac{n+2}{n} p \operatorname{div} \vec{u} - |\vec{\nabla} p| p^{\frac{1}{n+2}} H \left(\rho p^{-\frac{n}{n+2}}, \frac{\vec{\nabla} \rho \vec{\nabla} p}{(\vec{\nabla} \rho)^2} p^{-\frac{2}{n+2}}, \frac{|\vec{\nabla} p|}{|\vec{\nabla} \rho|} p^{-\frac{2}{n+2}} \right) \quad (16)$$

is a general solution of the system (15).

Thus we have proved the following

Theorem. *The system (5) is invariant with respect to the extended Galilean algebra $A\tilde{G}(1, n)$ (2), (8) when it has the form*

$$\begin{cases} \vec{u}_0 + (\vec{u} \cdot \vec{\nabla}) \vec{u} + \frac{1}{\rho} \vec{\nabla} p = 0, \\ \rho_0 + \operatorname{div}(\rho \vec{u}) = 0, \\ p_0 + (\vec{u} \cdot \vec{\nabla}) p + \frac{n+2}{n} p \operatorname{div} \vec{u} = \\ \quad |\vec{\nabla} p| p^{\frac{1}{n+2}} H \left(\rho p^{-\frac{n}{n+2}}, \frac{\vec{\nabla} \rho \vec{\nabla} p}{(\vec{\nabla} \rho)^2} p^{-\frac{2}{n+2}}, \frac{|\vec{\nabla} p|}{|\vec{\nabla} \rho|} p^{-\frac{2}{n+2}} \right) \end{cases} \quad (17)$$

where H is an arbitrary smooth function.

Notation 1. At $H = 0$ the result of the theorem is the same as one obtained by Ovsyannikov in [2].

Notation 2. By substitution

$$p = \lambda \frac{n}{n+2} P^{\frac{n+2}{n}}, \quad \lambda = \text{const} \quad (18)$$

the system (17) reduces to

$$\begin{cases} \vec{u}_0 + (\vec{u} \cdot \vec{\nabla}) \vec{u} + \frac{\lambda}{\rho} P^{\frac{2}{n}} \vec{\nabla} P = 0, \\ \rho_0 + \operatorname{div}(\rho \vec{u}) = 0, \\ P_0 + \operatorname{div}(P \vec{u}) = P^{\frac{1}{n}} |\vec{\nabla} P| f \left(\frac{P}{\rho}, \frac{\vec{\nabla} \rho \vec{\nabla} P}{(\vec{\nabla} \rho)^2}, \frac{|\vec{\nabla} P|}{|\vec{\nabla} \rho|} \right). \end{cases} \quad (19)$$

References

- [1] Fushchych W., Shtelen W. and Serov N., Symmetry Analysis and Exact Solutions of Equations of Nonlinear Mathematical Physics, Dordrecht, Kluwer Academic Publishers, 1993, 436p.
- [2] Ovsyannikov L.W., Lectures on the Basis of Gas Dynamics, Moscow, Nauka, 1981, 368p.