Global analysis of almost periodic positive solution of a multispecies discrete Gilpin-Ayala mutualism system with feedback controls

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Abstract. This paper discusses a multispecies discrete Gilpin-Ayala mutualism system with feedback controls. We firstly obtain the permanence of the system. Assuming that the coefficients in the system are almost periodic positive sequences, we obtain the sufficient conditions for the existence of a unique almost periodic positive solution which is globally attractive.

Keywords: Global attractivity; almost periodic solution; discrete; Gilpin-Ayala mutualism system; permanence

1 Introduction

As we all known, investigating the almost periodic positive solutions of discrete population dynamics model with feedback controls has more extensively practical application value (see [1–3] and the references cited therein). Wang [1] considered a nonlinear single species discrete system with feedback control

\[
\begin{aligned}
N(n+1) &= N(n) \exp \big[ p(n) \left( 1 - \frac{N^0(n)}{k(n)} - c(n)u(n) \right) \big], \\
\Delta u(k) &= -a(n)u(n) + b(n)N^0(n).
\end{aligned}
\]

Some sufficient conditions which assure the unique existence and global attractivity of almost periodic positive solution are obtained.

In this paper, we investigate the dynamic behavior of the following multispecies discrete Gilpin-Ayala mutualism model with feedback controls

\[
\begin{aligned}
x_i(k+1) &= x_i(k) \exp \left\{ a_i(k) - b_i(k)(x_i(k))^\theta_i + \sum_{j=1,i \neq j}^{n} \frac{c_{ij}(k)(x_j(k))^\theta_j}{d_{ij} + (x_j(k))^\theta_j} - e_i(k)u_i(k) \right\}, \\
\Delta u_i(k) &= -f_i(k)u_i(k) + \sum_{j=1}^{n} g_{ij}(k)x_j(k),
\end{aligned}
\]

(1.1)

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where $i = 1, 2, \ldots, n; x(k)$ stand for the densities of species at the $k$th generation, $a_i(k)$ represent the natural growth rates of species $x_i$ at the $k$th generation, $b_i(k)$ are the intra specific effects of the $k$th generation of species $x_i$ on own population, and $c_{ij}(k)$ measure the inter specific mutualism effects of the $k$th generation of species $x_j$ on species $x_i(i, j = 1, 2, \ldots, n, i \neq j)$, $d_{ij}$ are positive control constants. $\theta_i$ and $\theta_{ij}$ are positive constants.

Throughout this paper, we assume that:
(H1) $\{a_i(k)\}, \{b_i(k)\}, \{c_{ij}(k)\}, \{e_i(k)\}, \{f(k)\}$ and $\{g_{ij}(k)\}$ are bounded nonnegative almost periodic sequences such that:

$0 < d_i \leq a_i(k) \leq a_i^n, 0 < b_i \leq b_i(k) \leq b_i^n, 0 < c_{ij} \leq c_{ij}(k) \leq c_{ij}^n, 0 < e_i \leq e_i(k) \leq e_i^n, 0 < f \leq f(k) \leq f^n, 1.0 < g_{ij} \leq g_{ij}(k) \leq g_{ij}^n$, and

From the point of view of biology, we assume that $\mathbf{x}(0) = (x_1(0), x_2(0), \ldots, x_n(0), u_1(0), u_2(0), \ldots, u_n(0)) > 0$. It is easy to see that, for given $\mathbf{x}(0)$, the system (1) has a positive sequence solution $\mathbf{x}(k) = (x_1(k), x_2(k), \ldots, x_n(k), u_1(k), u_2(k), \ldots, u_n(k))(k \in \mathbb{Z}^+)$ passing through $\mathbf{x}(0)$.

2 Preliminaries

Now, we present some results which will play an important role in the proof of the main result.

**Definition 2.1**[4] A sequence $x: \mathbb{Z} \to \mathbb{R}$ is called an almost periodic sequence if the $\varepsilon$-translation set of $x$

$$E\{\varepsilon, x\} = \{\tau \in \mathbb{Z} : \|x(n + \tau) - x(n)\| < \varepsilon, \forall n \in \mathbb{Z}\}$$

is a relatively dense set in $\mathbb{Z}$ for all $\varepsilon > 0$; that is, for any given $\varepsilon > 0$; there exists an integer $l(\varepsilon) > 0$ such that each interval of length $l(\varepsilon)$ contains an integer $\tau \in E\{\varepsilon, x\}$ with

$$\|x(n + \tau) - x(n)\| < \varepsilon, \forall n \in \mathbb{Z}.\$$

$\varepsilon$ is called an $\varepsilon$-translation number of $x(n)$.

**Definition 2.2**[5] A sequence $x: \mathbb{Z}^+ \to \mathbb{R}$ is called an asymptotically almost periodic sequence if

$$x(n) = p(n) + q(n), \forall n \in \mathbb{Z}^+,$$

where $p(n)$ is an almost periodic sequence and

$$\lim_{n \to +\infty} q(n) = 0.$$

**Theorem 2.3**[5] $\{x(n)\}$ is an asymptotically almost periodic sequence if and only if, for any sequence $m_i \subset \mathbb{Z}$ satisfying $m_i > 0$ and $m_i \to \infty$ as $i \to \infty$ there exists a subsequence $\{m_{i_k}\} \subset \{m_i\}$ such that the sequence $\{x(n + m_{i_k})\}$ converges uniformly for all $n \in \mathbb{Z}^+$ as $k \to \infty$.

**Theorem 2.4** ([6]) Assume that sequence $\{x(n)\}$ satisfies $x(n) > 0$ and

$$x(n + 1) \leq x(n) \exp{\alpha(n) - b(n)x^n(n)}.$$

For $n \in \mathbb{N}$, where $a(n)$ and $b(n)$ are nonnegative sequences bounded above and below by positive constants, $\alpha$ is a positive constant. Then

$$\lim_{n \to +\infty} \sup_x x(n) \leq \left( \frac{1}{\alpha b} \right)^{\frac{1}{a^c}} \exp\{a^n - \frac{1}{a}\}.$$

**Theorem 2.5**([7]) Assume that sequence $\{x(n)\}$ satisfies

$$x(n + 1) \geq x(n) \exp{\alpha(n) - b(n)x^n(n)}, n \geq N_0,$$

and $\limsup_{n \to +\infty} x(n) < x^*$, $a(n)$ and $b(n)$ are non-negative sequences bounded above and below by positive constants, $\alpha$ is a positive constant and $N_0 \in \mathbb{N}$. Then

$$\liminf_{n \to +\infty} x(n) \geq \min\left\{ \left( \frac{a^l}{b^a} \right)^{\frac{1}{b^n}} \exp\{a - b\} \right\}, (\frac{a^l}{b^a})^{\frac{1}{b^n}}.$$

**Theorem 2.6** ([8]) Assume that $A > 0$ and $y(0) > 1$, and further suppose that

$$y(n + 1) \leq A y(n) + B(n), n = 1, 2, 3, \ldots.$$
Then for any integer \( k \leq n \),
\[
y(n) \leq A^k y(n-k) + \sum_{i=0}^{k-1} A^i B(n-i-1)
\]
Especially, if \( A < 1 \) and \( B \) is bounded above with respect to \( M \), then
\[
\limsup_{n \to \infty} y(n) \leq \frac{M}{1-A}
\]

**Theorem 2.7** ([8]) Assume that \( A > 0 \) and \( y(0) > 1 \), and further suppose that
\[
y(n+1) \geq A y(n) + B(n), \quad n = 1, 2, 3, \ldots
\]
Then for any integer \( k \leq n \),
\[
y(n) \geq A^k y(n-k) + \sum_{i=0}^{k-1} A^i B(n-i-1)
\]
Especially, if \( A < 1 \) and \( B \) is bounded below with respect to \( m \), then
\[
\liminf_{n \to \infty} y(n) \geq -\frac{m}{1-A}
\]

### 3 Permanence

In this section, we establish the permanence result for system (1.1).

**Proposition 3.1** Assume that the condition (H1) holds, furthermore,
\[
a^i_j - e^u N_j > 0 \quad (3.1)
\]

Then system (1.1) is permanent, that is, there exist positive constants \( m_i, M_i, n_i, N_i (i=1, 2, \ldots, n) \) which are independent of the solutions of system (1.1), such that for any positive solution \((x_1(k), x_2(k), \ldots, x_n(k), u_1(k), u_2(k), \ldots, u_n(k))\) of system (1.1), one has:
\[
m_i \leq \liminf_{k \to \infty} x_i(k) \leq \limsup_{k \to \infty} x_i(k) \leq M_i,
\]
\[
n_i \leq \liminf_{k \to \infty} u_i(k) \leq \limsup_{k \to \infty} u_i(k) \leq N_i,
\]

Where
\[
M_i = \frac{1}{b^i_j} \exp\{a^u_j + \sum_{j=1, j \neq i}^{n} c^u_{j} - 1\},
\]
\[
m_i = \frac{a^i_j - e^u_j N_j}{2b^u_j} \min\{1, \exp\{a^i_j - e^u_j N_j - b^u_j M_i\}\},
\]
\[
N_i = \frac{1}{f^i_j} \sum_{j=1}^{n} g^u_j M_j, \quad n_i = \frac{1}{f^i_j} \sum_{j=1}^{n} g^u_j m_j.
\]

**Proof.** The proof of Proposition 3.1 is similar to that of Theorem 3.1 in Ref. [3]. So we omit the detail here.

We denote by \( \Omega \) the set of all solutions \((x_1(k), x_2(k), \ldots, x_n(k), u_1(k), u_2(k), \ldots, u_n(k))\) of system (1.1) satisfying \( m_i \leq x_i(k) \leq M_i, \quad n_i \leq u_i(k) \leq N_i (i=1, 2, \ldots, n) \) for all \( k \in \mathbb{Z}^+ \).

**Proposition 3.2** ([3]) Assume that the conditions (H1) and (3.1) hold. Then \( \Omega \neq \Phi \).

### 4 Almost periodic solution

The main results of this paper concern the global attractivity of almost periodic positive solution of system (1.1) with conditions (H1) and (3.1).

**Theorem 4.1** Assume that (H1), (3.1) and
\[
(H2) \quad \rho_j = \max\{\left\| 1 - \theta \rho_j b^u_j m^j_0 \right\| + \sum_{j=1, j \neq i}^{n} \frac{\theta_j c^u_j M^j_0}{d^j} + e^u_j < 1,
\]

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\[ \phi_i = 1 - f_i^j + \sum_{j=1}^{n} g_j^w M_j < 1, i = 1, 2, \ldots, n, \]

hold. Then any positive solution \((x_1(k), x_2(k), \ldots, x_n(k), u_1(k), u_2(k), \ldots, u_n(k))\) of system (1.1) is globally attractive.

**Proof.** Assume that \(p_1(k), p_2(k), \ldots, p_n(k), v_1(k), v_2(k), \ldots, v_n(k)\) is a solution of system (1.1) satisfying (H1) and (3.1). Let

\[
(x_i(k) = p_i(k) \exp\{q_i(k)\}, u_i(k) = v_i(k) + w_i(k).
\]

Since

\[
q_i(k + 1) = \ln x_i(x + 1) - \ln p_i(x + 1) = q_i(k)(1 - \theta_i b_i(k)[p_i(k) \exp(\theta_i \xi_i(k)q_i(k))]^\theta_i)
+ \sum_{j=1, j \neq i}^{n} d_{ij} \theta_j c_j(k)q_j(k)[p_j(k) \exp(\theta_j \xi_j(k)q_j(k))]^\theta_j
+ \sum_{j=1}^{n} \theta_j c_j^w(M_j + \epsilon)^\theta_j - \epsilon w_i(k),
\]

where \(\lambda_i(k), \lambda_j(k) \in (0, 1)\).

Similarly, we get

\[
w_i(k + 1) = u_i(k + 1) - v_i(k + 1)
= (1 - f_i(u))w_i(k) + \sum_{j=1}^{n} g_j^w(p_j(k)q_j(k) \exp(\theta_j \xi_j(k)q_j(k)), wh \xi_i(k) \in (0, 1).
\]

To complete the proof, it suffices to show that

\[
\lim_{k \to +\infty} q_i(k) = 0, \lim_{k \to +\infty} w_i(k) = 0.
\]

In view of (H2), we can choose \(\epsilon > 0\) such that

\[
\rho_i^x = \max\{\max \{q_i(0)\}, \max \{w_i(0)\}\},
\]

\[
\phi_i^x = 1 - f_i^x + \sum_{j=1}^{n} g_j^w(M_j + \epsilon) < 1, i = 1, 2, \ldots, n.
\]

Let \(\rho = \max \{\rho_i^x, \phi_i^x\}\), then \(\rho < 1\). According to Proposition 3.1, there exists a positive integer \(k_0 \in Z^+\) such that

\[
m_i - \epsilon \leq x_i(k) \leq M_i + \epsilon, m_i - \epsilon \leq u_i(k) \leq M_i + \epsilon,
\]

for \(k \geq k_0\).

From (4.1), we get

\[
|q_i(k + 1)| = \max\{\max_{1 \leq i \leq n} |q_i(k)|, \max_{1 \leq i \leq n} |w_i(k)|\},
\]

\[
|q_i(k)| + \sum_{j=1}^{n} \theta_j c_j^w(M_j + \epsilon)^\theta_j |q_j(k)| + \epsilon w_i(k), (4.1)
\]

\[
|w_i(k + 1)| = (1 - f_i^x) |w_i(k)| + \sum_{j=1}^{n} g_j^w(M_j + \epsilon) |q_j(k)| < 1,
\]

for \(k \geq k_0\). In view of (4.3), we get

\[
\max_{1 \leq i \leq n} \max_{1 \leq i \leq n} |q_i(k)|, \max_{1 \leq i \leq n} |w_i(k)| \leq \rho \max_{1 \leq i \leq n} |q_i(k)|, \max_{1 \leq i \leq n} |w_i(k)|, k \geq k_0.
\]

This implies

\[
\max_{1 \leq i \leq n} |q_i(k)|, \max_{1 \leq i \leq n} |w_i(k)| \leq \rho^{k - k_0} \max_{1 \leq i \leq n} |q_i(k_0)|, \max_{1 \leq i \leq n} |w_i(k_0)|, k \geq k_0.
\]

Then (4.2) holds and we can obtain

\[
\lim_{k \to +\infty} |x_i(k) - p_i(k)| = 0, \lim_{k \to +\infty} |w_i(k) - v_i(k)| = 0.
\]

Therefore, positive solution \((x_1(k), x_2(k), \ldots, x_n(k), u_1(k), u_2(k), \ldots, u_n(k))\) of system (1.1) is globally attractive.

**Theorem 4.2** Assume that (3.1), (H1) and (H2) hold. Then system (1.1) admits a unique almost periodic positive solution which is globally attractive.

**Proof.** It follows from Proposition 3.2 that there exists a solution \((x_1(k), x_2(k), \ldots, x_n(k), u_1(k), u_2(k), \ldots, u_n(k))\)
\[\ln x_i(k+\delta_p) - \ln x_i(k+\delta_q) = \frac{1}{\theta_x(k,p,q)}[(x_i(k+\delta_p))^\theta_x - (x_i(k+\delta_q))^\theta_x], \]

\[\ln x_i(k+\delta_p) - \ln x_i(k+\delta_q) = \frac{1}{\eta(k,p,q)}[x_i(k+\delta_p) - x_i(k+\delta_q)]\]

where \(\xi(k,p,q)\) lies between \((x_i(k+\delta_p))^\theta_x\) and \((x_i(k+\delta_q))^\theta_x\), and \(\eta(k,p,q)\) lies between \(x_i(k+\delta_p)\) and \(x_i(k+\delta_q)\). Then

\[\left|(x_i(k+\delta_p))^\theta_x - (x_i(k+\delta_q))^\theta_x\right| \leq \theta_x M_i^\theta_x \left|\ln x_i(k+\delta_p) - \ln x_i(k+\delta_q)\right|.\]

From the first equation of (1.1), we have

\[\left|\ln x_i(k+1+\delta_p) - \ln x_i(k+1+\delta_q)\right| = \left|\ln x_i(k+\delta_p) - \ln x_i(k+\delta_q)\right|\]

\[+ a_i(k+\delta_p) - b_i(k+\delta_p)\left(x_i(k+\delta_p)^\theta_x\right) + \sum_{j=1}^{n} c_{ij}(k+\delta_p)\frac{(x_j(k+\delta_p))^\theta_x}{d_{ij} + (x_j(k+\delta_p))^\theta_x}\]

\[- a_i(k+\delta_q) - b_i(k+\delta_q)\left(x_i(k+\delta_q)^\theta_x\right) + \sum_{j=1}^{n} c_{ij}(k+\delta_q)\frac{(x_j(k+\delta_q))^\theta_x}{d_{ij} + (x_j(k+\delta_q))^\theta_x}\]

\[+ \left|e_i(k+\delta_p) - e_i(k+\delta_q)\right|\left[u_i(k+\delta_p) - u_i(k+\delta_q)\right]\]

\[\leq \left|\ln x_i(k+\delta_p) - \ln x_i(k+\delta_q) - b_i(k+\delta_p)\left[x_i(k+\delta_p)^\theta_x\right] - \left(x_i(k+\delta_q)^\theta_x\right)\right|\]

\[+ \left|a_i(k+\delta_p) - a_i(k+\delta_q)\right| + \left|b_i(k+\delta_p) - b_i(k+\delta_q)\right|\left(x_i(k+\delta_p)^\theta_x\right) + \left(\sum_{j=1}^{n} c_{ij}(k+\delta_p)\left(x_j(k+\delta_p)^\theta_x\right) - \left(x_j(k+\delta_q)^\theta_x\right)\right)\]

\[+ \left|e_i(k+\delta_p) - e_i(k+\delta_q)\right|\left[u_i(k+\delta_p) - u_i(k+\delta_q)\right].\]

Let \(\varepsilon_1\) be an arbitrary positive number. By the almost periodicity of \(\{a_i(k)\}, \{b_i(k)\}, \{e_i(k)\}\) and the boundedness of \((x_i(k), x_{i2}(k), \ldots, x_{in}(k), u_1(k), u_2(k), \ldots, u_n(k))\), it follows from Theorem 2.3 that there exists a positive integer \(K_1 = K_1(\varepsilon_1)\) such that, for any \(\delta_p \geq \delta_q \geq K_1\) and \(k \in \mathbb{Z}\) (if necessary, we can choose subsequences of \(\delta_q\) and \(\delta_p\)),

\[\left|a_i(k+\delta_q) - a_i(k+\delta_p)\right| < \frac{\varepsilon_1}{4}, \left|b_i(k+\delta_q) - b_i(k+\delta_p)\right|\left(x_i(k+\delta_p)^\theta_x\right) < \frac{\varepsilon_1}{4}\]

\[\sum_{j=1}^{n} \left|c_{ij}(k+\delta_q) - c_{ij}(k+\delta_p)\right|\left(x_j(k+\delta_p)^\theta_x\right) < \frac{\varepsilon_1}{4}, \left|e_i(k+\delta_q) - e_i(k+\delta_p)\right|\left[u_i(k+\delta_p) - u_i(k+\delta_q)\right] < \frac{\varepsilon_1}{4}.\]

It follows from (4.5)-(4.8) that, for \(k \in \mathbb{Z}\) and \(\delta_p \geq \delta_q \geq K_1\),

\[\left|\ln x_i(k+1+\delta_p) - \ln x_i(k+1+\delta_q)\right| \leq \max\left|1 - \theta_x b_i^{'\theta_x}(m_i - \varepsilon)\right|, \left|1 - \theta_x b_i^{'\theta_x}(M_i + \varepsilon)\right|\left|\ln x_i(k+\delta_p) - \ln x_i(k+\delta_q)\right|\]

\[+ \sum_{j=1}^{n} \theta_x c_{ij}^{'\theta_x}(M_j + \varepsilon)\left|\ln x_j(k+\delta_p) - \ln x_j(k+\delta_q)\right| + \left|e_i(k+\delta_p)\right|\left[u_i(k+\delta_p) - u_i(k+\delta_q)\right].\]

Similar, we get

\[\left|u_i(k+1+\delta_p) - u_i(k+1+\delta_q)\right| \leq \left(1 - f_i^{'\varepsilon}\right)\left|u_i(k+\delta_p) - u_i(k+\delta_q)\right| + \sum_{j=1}^{n} g_{ij}^{'\varepsilon} M_j \left|\ln x_j(k+\delta_p) - \ln x_j(k+\delta_q)\right| + \varepsilon_i.\]

In view of (H2), we can choose an \(\varepsilon_1 > 0\) such that
\[ \rho_i^\varphi = \max \left\{ \left| 1 - \theta_n b'_i \left( m_i - \varepsilon_i \right)^\varphi \right|, \left| 1 - \theta_n b'_i \left( M_i + \varepsilon_i \right)^\varphi \right| + \sum_{j=1}^n \frac{\theta_j \varepsilon_j^\varphi (M_j + \varepsilon_j)^\varphi}{d_j} + \varepsilon_i, i < 1, \right. \]

\[ \varphi_i^\varphi = 1 - f_i^\varphi + \sum_{j=1}^n g_{ij}^\varphi (M_j + \varepsilon_j) + \varepsilon_i < 1, i = 1, 2, \ldots, n. \]

Let \( \rho_i = \max \{ \rho_i^\varphi, \varphi_i^\varphi \} \). Then \( 0 < \rho_i < 1 \). In view of (4.9) and (4.10), we get

\[ \max \{ |\ln x_i - \ln x_j|, |u_i - u_j|, |v_i - v_j| \} \leq \rho_i \max \{ \ln x_i, \ln x_j, u_i, u_j, v_i, v_j \} \]

For convenience, we introduce \( \varphi (k, \delta_p, \delta_q) \) through

\[ \varphi (k, \delta_p, \delta_q) = \max \{ |\ln x_i - \ln x_j|, |u_i - u_j|, |v_i - v_j| \} \geq \delta_q, \]

Then

\[ \varphi (k, \delta_p, \delta_q) < \rho_i \max \{ \varphi (k-1, \delta_p, \delta_q) \} + \varepsilon_i, \]

\[ \varphi (k-1, \delta_p, \delta_q) < \rho_i \max \{ \varphi (k-2, \delta_p, \delta_q) \} + \varepsilon_i, \]

\[ \varphi (1, \delta_p, \delta_q) < \rho_i \max \{ \varphi (0, \delta_p, \delta_q) \} + \varepsilon_i. \]

And we have

\[ \varphi (k, \delta_p, \delta_q) < \rho_i^k \max \{ \varphi (0, \delta_p, \delta_q) \} + \frac{1 - \rho_i^k}{1 - \rho_i} \varepsilon_i \]

for \( k \in \mathbb{Z}^+ \).

Since \( \rho_i < 1 \), for arbitrary \( \varepsilon > 0 \), there exists a positive integer \( K = K(\varepsilon) > K \) such that for any \( \delta_q \geq \delta_p \geq K\)

\[ \varphi (k, \delta_p, \delta_q) < \frac{\varepsilon}{\max \{ M_i, 1 \}}. \]

This combined with (4.6) gives us

\[ |x_i(k + \delta_p) - x_i(k + \delta_q)| < \varepsilon, |u_i(k + \delta_p) - u_i(k + \delta_q)| < \varepsilon. \]

It follows from Theorem 2.3 that the sequences \( \{x_i(k)\} \) and \( \{u_i(k)\} \) are asymptotically almost periodic. Thus we can express

\[ x_i(k) = p_i(k) + q_i(k), u_i(k) = v_i(k) + w_i(k). \]

where \( \{p_i(k)\} \) and \( \{v_i(k)\} \) are almost periodic in \( k \in \mathbb{Z} \) and \( q_i(k) \to 0 \) and \( w_i(k) \to 0 \) as \( k \to \infty \). In the following we show that \( \{p_i(k), p_2(k), \ldots, p_n(k), v_1(k), v_2(k), \ldots, v_n(k)\} \) is an almost periodic solution of system (1.1).

In the following we show that \( \{p_1(k), p_2(k), \ldots, p_n(k), v_1(k), v_2(k), \ldots, v_n(k)\} \) is an almost periodic positive solution of system (1.1).

From the properties of an almost periodic sequence, there exists an integer valued sequence \( \{\delta_p\}, \delta_p \to +\infty \) as \( p \to +\infty \), such that

\[ a_i(k + \delta_p) \to a_i(k), b_i(k + \delta_p) \to b_i(k), c_i(k + \delta_p) \to c_i(k), \]

\[ e_i(k + \delta_p) \to e_i(k), f_i(k + \delta_p) \to f_i(k), g_i(k + \delta_p) \to g_i(k), \]

\[ \text{asp} \to +\infty. \]

It is easy to know that \( x_i(k + \delta_p) \to p_i(k), u_i(k + \delta_p) \to v_i(k) \) as \( p \to \infty \), then we have

\[ p_i(k + 1) = \lim_{p \to \infty} x_i(k + 1 + \delta_p) = p_i(k) \exp \left\{ a_i(k) - b_i(k)(p_i(k))^{\varepsilon_i} + \sum_{j=1}^n \frac{c_j(x_j(k))^{\varepsilon_j}}{d_j + (x_j(k))^{\varepsilon_j}} - e_i(k) v_i(k) \right\}, \]

\[ v_i(k + 1) = \lim_{p \to \infty} u_i(k + 1 + \delta_p) = [1 - f_i(k)] v_i(k) + \sum_{j=1}^n g_{ij}(k) p_j(k). \]

This prove that \( p(k) = \{p_1(k), p_2(k), \ldots, p_n(k), v_1(k), v_2(k), \ldots, v_n(k)\} \) satisfied system (1.1), and \( p(k) \) is a positive almost periodic solution of system (1.1).

Now, we show that there is only one positive almost periodic solution of system (1.1). For any two positive almost periodic solutions \( \{p_1(k), p_2(k), \ldots, p_n(k), v_1(k), v_2(k), \ldots, v_n(k)\} \) and \( \{z_1(k), z_2(k), \ldots, \}

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of system (1.1), we claim that \( p_i(k) = z_i(k), \ v_i(k) = l_i(k), \ (i = 1, 2, \ldots, n) \) for all \( k \in \mathbb{Z}^+ \). Otherwise there must be at least one positive integer \( K^* \in \mathbb{Z}^+ \) such that \( p_i(K^*) \neq z_i(K^*) \) or \( v_j(K^*) \neq l_j(K^*) \) for a certain positive integer \( j \), i.e.,

\[
\Omega_1 = \left| p_i(K^*) - z_i(K^*) \right| > 0, \quad \Omega_2 = \left| v_j(K^*) - l_j(K^*) \right| > 0
\]

So we can easily know that

\[
\Omega_1 = \lim_{k \to +\infty} \left| p_i(K^* + \delta) - p_i(K^*) \right| = \lim_{k \to +\infty} \left| p_i(k) - z_i(k) \right| > 0,
\]

\[
\Omega_2 = \lim_{k \to +\infty} \left| v_j(K^* + \delta) - l_j(K^*) \right| = \lim_{k \to +\infty} \left| v_j(k) - l_j(k) \right| > 0,
\]

which is a contradiction to (4.4). Thus \( p_i(k) = z_i(k), \ v_i(k) = l_i(k), \ (i = 1, 2, \ldots, n) \) hold for all \( k \in \mathbb{Z}^+ \). Therefore, system (1.1) admits a unique almost periodic positive solution which is globally attractive.

This completes the proof of Theorem 4.2.

5 Example and numerical simulation

In this section, we give the following example to check the feasibility of our result.

**Example** Consider the following almost periodic discrete Gilpin-Ayala mutualism system with feedback controls

\[
\begin{align*}
x_1(k+1) &= x_1(k) \exp \left\{ 1.1 - 0.022 \sin(\sqrt{3}k) - (1.05 + 0.013 \sin(\sqrt{5}k)) (x_1(k))^{1/2} \right\} \\
&\quad + \left( 0.025 - 0.001 \cos(\sqrt{2}k) \right) x_2(k) + \left( 0.02 + 0.015 \cos(\sqrt{3}k) \right) x_3(k) \\
&\quad + \left( 0.025 - 0.002 \cos(\sqrt{5}k) \right) x_4(k), \\
x_2(k+1) &= x_2(k) \exp \left\{ 1.15 - 0.025 \sin(\sqrt{2}k) - (1.085 + 0.015 \sin(\sqrt{3}k)) (x_2(k))^{1/2} \right\} \\
&\quad + \left( 0.025 + 0.003 \cos(\sqrt{5}k) \right) x_1(k) + \left( 0.025 - 0.002 \cos(\sqrt{2}k) \right) x_3(k) \\
&\quad + \left( 0.025 + 0.004 \sin(\sqrt{2}k) \right) x_4(k), \\
x_3(k+1) &= x_3(k) \exp \left\{ 1.25 - 0.03 \sin(\sqrt{5}k) - (1.1 - 0.024 \sin(\sqrt{2}k)) (x_3(k))^{1/2} \right\} \\
&\quad + \left( 0.03 - 0.002 \cos(\sqrt{2}k) \right) x_1(k) + \left( 0.028 + 0.0015 \cos(\sqrt{3}k) \right) x_2(k) \\
&\quad + \left( 0.02 + 0.002 \cos(\sqrt{5}k) \right) x_4(k), \\
\Delta u_1(k) &= - (0.93 - 0.03 \sin(\sqrt{2}k)) u_1(k) + (0.015 + 0.005 \sin(\sqrt{3}k)) x_1(k) \\
&\quad + (0.013 - 0.004 \sin(\sqrt{5}k)) x_2(k) + (0.024 - 0.005 \cos(\sqrt{3}k)) x_3(k), \\
\Delta u_2(k) &= - (0.924 - 0.04 \sin(\sqrt{2}k)) u_1(k) + (0.018 - 0.004 \sin(\sqrt{5}k)) x_1(k) \\
&\quad + (0.015 - 0.005 \cos(\sqrt{2}k)) x_2(k) + (0.014 + 0.004 \sin(\sqrt{2}k)) x_3(k), \\
\Delta u_3(k) &= - (0.936 - 0.035 \cos(\sqrt{5}k)) u_1(k) + (0.017 - 0.006 \cos(\sqrt{2}k)) x_1(k) \\
&\quad + (0.013 - 0.005 \sin(\sqrt{3}k)) x_2(k) + (0.014 + 0.005 \cos(\sqrt{2}k)) x_3(k).
\end{align*}
\]

By simple computation, we derive

\( \rho_1 \approx 0.101, \ \rho_2 \approx 0.211, \ \rho_3 \approx 0.108, \ \varphi_1 \approx 0.009, \ \varphi_2 \approx 0.053, \ \varphi_3 \approx 0.101. \)

It is easy to see that the conditions of Theorem 4.2 are verified. Therefore, system (5.1) has a unique positive almost periodic positive solution which is globally attractive. Our numerical simulations support our results (see Figure1).
Figure 1. Dynamic behavior of positive almost periodic solution \((x_1(k), x_2(k), x_3(k), u_1(k), u_2(k), u_3(k))\) of system (5.1) with the three initial conditions \((1.09, 1.17, 1.2, 0.07, 0.07, 0.046), (1.02, 1.1, 1.1, 0.06, 0.06, 0.053)\) and \((1.13, 1.05, 1.25, 0.064, 0.047, 0.061)\) for \(k \in [1, 70]\), respectively.

6 Concluding remarks

In this paper, assuming that the coefficients in system (1.1) are bounded non-negative almost periodic positive sequences, we obtain the sufficient conditions for the existence of a unique almost periodic positive solution which is globally attractive. By comparative analysis, we find that when the coefficients in system (1.1) are almost periodic, the existence of a unique almost periodic positive solution of system (1.1) is determined by the global attractivity of system (1.1), which implies that there is no additional condition to add.

Furthermore, for the almost periodic multispecies discrete Gilpin-Ayala mutualism system with feedback controls and timed delays, we would like to mention here the question of how to study the almost periodicity of the system and whether the existence of a unique almost periodic positive solution is determined by the global attractivity of the system or not. It is, in fact, a very challenging problem, and we leave it for our future work.
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